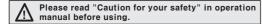
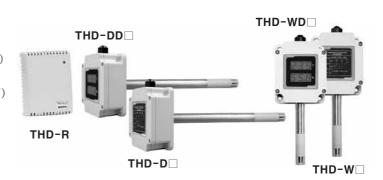
Indoor, Duct & Wall mounting type Temperature/Humidity transducer

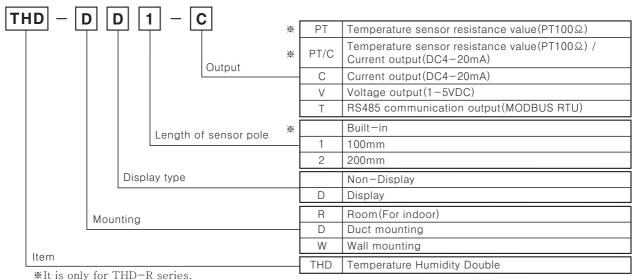
■ Features

- Compact design
- •Built-in temp./humidity sensor
- •7 Segment LED Display (THD-DD/THD-WD)
- ●Various output modes DC4-20mA, 1-5VDC, RS485 (MODBUS RTU)
- •Wide range of temp./humidity measurement -19.9 ~ 60.0 ℃ / 0.0 ~ 99.9%RH
- ●Communication speed: 115200bps





Ordering information



Specifications

Model		THD-R-PT	THD-R-PT/C	THD-R-□	THD-D - C	THD-DD - C
Display type Non-indicating type 7S				7Segment LED Display		
Digit						3Digit for tempera -ture, humidity
Character size	9					10mm
Power supply				24VDC	±10%	
Power consun	nption			Max.	2.4W	
Measuring inp	out	Temperature (Built-in sensor)		Temperature, Humio	dity(Built-in sensor)	
Output	Temp.	PT100Ω res	stance value			(MODDIIO DAII)
Output	Humidity		DC4-20mA ●1-5VDC ●RS485			(MODBUS RTU)
Measurement	Temp.		-19.9~60.0℃			
range	Humidity		0.0~99.9%RH(7	ΓHD-R series is requ	ired to attend for using	ng over 90%RH.)
	Temp.	Max. ±0.8℃	-19.9~5.0°C ∶ Max.	±1.0℃, 5.0~40.0℃	: Max. ±0.5℃, 40.0~	60.0℃: Max. 1.0℃
Accuracy	Humidity			at 30~70%RH ~45℃)	90 ±55. 70 ±44. 60 ±33. 40 ±4. 10 ±5. ±10	.0%RH 0%RH 0%RH 0%RH 0%RH 0%RH .0%RH .0%RH 5

C-83 Autonics

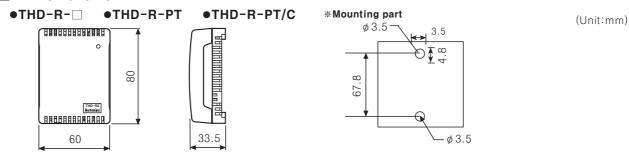
Temperature/Humidity Transducer

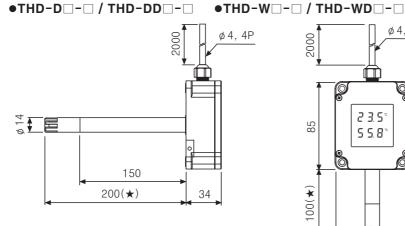
■ Specifications

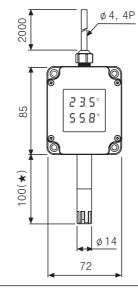
Model		THD-R-PT	THD-R-PT/C	THD-R-□	THD-D THD-W THD-W	THD-DD - THD-WD - THD-WD		
Sampling period ———				Fixed	0.5sec			
Insulatio	on resistance			Min. 100MΩ (500VDC mega)			
Dielectri	ic strength			500VAC 50/60	Hz for 1 minute			
Noise st	trength		±0.3kV the s	quare wave noise(pul	se width:1 μ s) by the n	oise simulator		
\/ilawatiaw	Mechanical		0.75mm amplitude at frequency of 10~55Hz in each of X, Y, Z directions for 1hour					
Vibration	Malfunction		0.5mm amplitude at	0.5mm amplitude at frequency of 10~55Hz in each of X, Y, Z directions for 10minutes				
011-	Mechanical		30	00m/s ² (30G) in X, Y,	Z directions for 3 tim	ies		
Shock	Malfunction		10	00m/s ² (10G) in X, Y,	Z directions for 3 tim	es		
Protection	on		IP10 IP65 (Except sensing			sensing part.)		
Ambient	t temperature		-20 ~ 60°C (at non-freezing status)					
Storage temperature			-20 ~	60℃ (at non-freezing	status)			
Cable			Terminal type		4P, ∮4mm, Length:2m			
Unit weight			Approx. 55g Approx.			x. 160g		

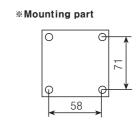
^{*}The allowable impedance of current output is max. 600Ω

Dimensions





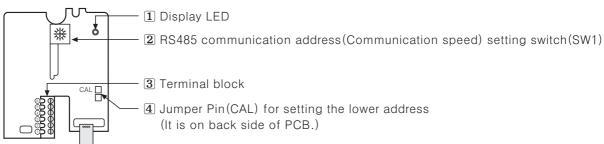




- ※(★) See the ordering information to select the one with 2 sensing poles.
- See the ordering information about display model, $THD-DD\Box-\Box$, $THD-WD\Box-\Box$.

Connections





Counter

(R) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

Tacho/ Speed/ Pulse meter

(G) Display unit

Sensor controller

(I) Switching power supply

Proximity sensor

(K) Photo electric sensor

(L) Pressure

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

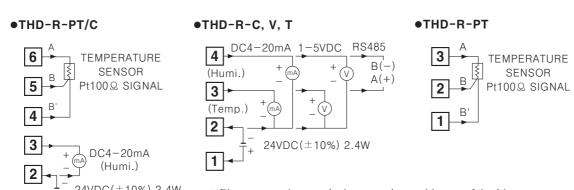
(O) Graphic panel

Field network device

(Q) Production stoppage models & replacement

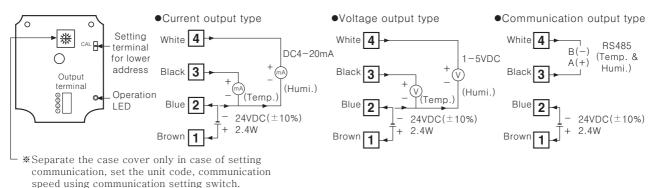
Autonics C - 84

THD Series



 $\ensuremath{\mathbb{X}}$ Please note the terminal connection and be careful with power supply.

OTHD-D / THD-W Series



■ Case detachment

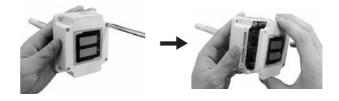
●THD-R Series

Unscrew the bolt on the bottom of product and separate the case.



●THD-D / THD-W Series

Unscrew 4 bolts on the top of product and separate the case.



Functions

OVoltage output

It transmits current temperature/humidity to other equipments, PC or recorder and outputs 1-5VDC. 1VDC output represents -19.9°C of temperature and 0.0% RH of humidity, 5VDC at 60°C of temperature and 99.9% RH of humidity. The temperature and humidity output are separated and the resolution is divided as 1,000.

Current output

It transmits current temperature/humidity to other equipments, PC or recorder and outputs DC4-20mA. It outputs DC4mA at -19.9° C of temperature and 0.0%RH of humidity, DC20mA at 60.0°C of temperature and 99.9%RH of humidity. The temperature and humidity output are separated and the resolution divisible by 1,000.

©Temperature sensor output(Pt 100 \Omega resistance value output)

It transmits current temperature/humidity to other equipments, recorder or thermometer. It outputs 100Ω at 0° C and 119.40Ω at 50° C. (TCR=3850 ppm/°C)

C-85 Autonics

Temperature/Humidity Transducer

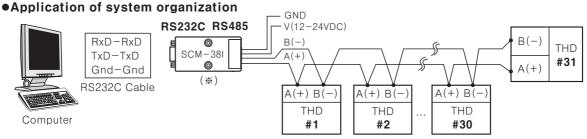
○RS485 communication output

It is used to transmit current temperature and humidity to other equipment.

Interface

Standard	EIA RS485
Number of connections	31, It is available to set address 01~31
Communication method	Half Duplex
Synchronous method	Asynchronous type
Communication distance	Within max. 800m
Communication speed	1200 ~ 115200bps(Available to set)
Start bit	1bit(Fixed)
Stop bit	1bit(Fixed)
Parity bit	None(Fixed)
Data bit	8bit(Fixed)
Protocol	MODBUS RTU

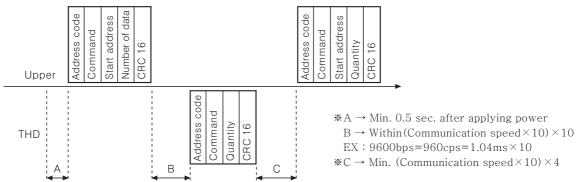
- *It is not possible to change parameter related to communication of THD under the communication with high order system.
- *Match the parameter of THD communication to be same as the high order system.
- *It is not allowed to set overlapping communication address at the same communication line.
- *Please use a proper twist pair for RS485 communication.



★SCM-38I made by Autonics is recommended to use with RS232C to RS485 converter.

Communication control ordering

- The communication method is MODBUS TRU(PI-MBUS-300 REV.J).
- •After 0.5sec of power supply into the high order system, it starts to communicate.
- •Initial communication will be started by the high order system. When a command comes out from the high order system, THD will respond.



Communication command and block

The format of query and response

Query

Address code	Command	Start address	Number of data	CRC16			
Calculation range of CRC16							

- ①Address code: This code which the high order system can identify THD by. It can be set within range 01H-1FH. ②Command: Read command for input register.
- ③Start address: The start address of input register to read (Start address), it is available to select 0000 and 0001 for start address. 16 bit data in the address 0000 indicates temperature value, 16 bit data in the address 0001 indicates humidity value.(Refer to MODBUS Mapping table.)
- ④Number of data: The number of 16 bit data from start address (No. of Points) It reads 2 of 16 bit data when start address is 0000 or reads 1 of 16 bit data is available when start address is 0001.
- ⑤CRC16: Check Sum which checks the whole frame and it is used for more reliable transmit/receive to check the error between transmitter and receiver.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Field network device

(Q) Production stoppage models & replacement

Autonics C-86

THD Series

Response

Address code	Command	Number of data	Temperature data	Humidity data	CRC16
		Calculation range	e of CRC16		

- ①Address code: The code, W the high order system can identify THD by. It can be set within range 01H-1FH.
- ②Command: Read command for input register.
- ③Number of data: The number of 8 bit data to send from start address(No. of Bytes)
- It reads 4 of 8 bit data when start address is 0000 or reads 2 of 8 bit data is available when start address is 0001. (Refer to MODBUS Mapping Table)
- Temperature data: To get a current temperature value, divide read value by 100.
 - Ex) When read data is 0x09B6, decimal value 2486, the current value is 2486/100=24.86°C.
- ⑤Humidity data: To get a current humidity value, divide read value by 100.
 - Ex) When read data is 0x12FE, decimal value 4862, the current value is 4862/100=48.62%RH.
- ⑥CRC16: Check Sum which checks the whole frame. (Refer to E-34 for CRC16 Table.)

Application

(Query): Address code(01), Start address(0000), The number of 16 Bit data to read(2) Check Sum(0x71CB)

01	04	00	00	00	02	71	СВ
Unit	Command	Start	code	Amount	of data	CRO	C16
number	Command	High order	Low order	High order	Low order	High order	Low order

(Response) : Address code (01), The number of 8 Bit data to read (4), Temperature (0x09B6), Humidity (0x12FE) CRC Check sum (0x94DE)

01	04	04	09	В6	12	FE	94	DE
Unit	Reponse	Amount	Tempera	ture data	Humidi	ty data	CR	C16
number	command	of data	High order	Low order	High order	Low order	High order	Low order

•Error processing(Slave → Master)

1. Non-supportable command

01	81	01	81	90
Unit number	Response command	Exception code	CRO	C16

- **X** Set a received highest bit and send it to response command and exception code 01. **X** Set a received highest bit and send it to response command and exception code 01.
- 2. The start code of queried data is not matched to the transmittable code

01	81	02	81	90
Unit number	Response command	Exception code	CR	C16

- *Set a received highest bit and send it to response command and exception code 02.
- 3. The number of queried data is bigger than transmittable one

01	84	03	Χ	X
Unit number	Response command	Exception code	CRO	C16

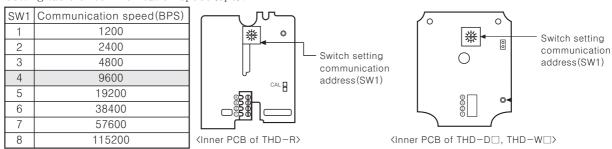
- *Set a received highest bit and send it to response command and exception code 03.
- 4. Abnormal processing for a received command

01	84	04	Χ	Χ
Unit number	Response command	Exception code	CRO	C16

^{*}Set a received highest bit and send it to response command and exception code 04.

Change the communication speed(THD-R Series)

- 1) Set SW1 to 0 and apply the power.
- 2) Operation LED is flashing.
- 3) Set a communication speed after choose SW1 within the range 1~8 and hold it for 3sec.
- 4) After set a communication speed, LED will be ON.
- *Factory default communication speed is 9600bps(SW 1:4) for communication speed.
- lphaIn order to change the communication speed, please turn off the power and repeat step 1) \sim 4).
- *Setting table of communication speed(bps).



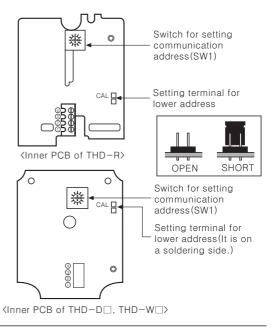
C-87 Autonics

Temperature/Humidity Transducer

○Change the communication address(THD-R Series)

- 1) Set CAL Jump pin and SW1 at new address, apply the power.
- 2) The communication address is changed automatically.
- *Factory default communication address is 01. (SW1:1, CAL Jump pin: Open)
- ※In order to change the communication address, please turn off the power and repeat step 1)~2).
- Setting table of communication address

CAL Pin	SW1	Add no.	CAL Pin	SW1	Add no.
OPEN	1	01	SHORT	0	16
OPEN	2	02	SHORT	1	17
OPEN	3	03	SHORT	2	18
OPEN	4	04	SHORT	3	19
OPEN	5	05	SHORT	4	20
OPEN	6	06	SHORT	5	21
OPEN	7	07	SHORT	6	22
OPEN	8	08	SHORT	7	23
OPEN	9	09	SHORT	8	24
OPEN	А	10	SHORT	9	25
OPEN	В	11	SHORT	А	26
OPEN	С	12	SHORT	В	27
OPEN	D	13	SHORT	С	28
OPEN	Е	14	SHORT	D	29
OPEN	F	15	SHORT	Е	30
_	_	_	SHORT	F	31



Caution for using

- 1. After checking the input specification, terminal polarity, connect the wires correctly.
- 2. Do not connect a wire, examine and repair when the power is applying.
- 3. Do not touch the temperature/humidity sensor module.
- 4. Please use THD-R series as wall mounting type.
- 5. Caution for cleaning
 - ①Use dry towel
 - 2Do not use acid, chrome acid and solvent but alcohol.
 - 3 Clean after turn off the power and turn it on 30 min. after.
- 6. Be sure that metal dust and wire-dregs are not flowed in the unit.
- 7. Connect the wires after checking polarity.
- 8. Please use separated line from high voltage line or power line in order to avoid inductive noise.
- 9. Keep away from the high frequency instruments. (High frequency welding machine & sewing machine, big capacitive SCR controller)
- 10. The switch or circuit breaker should be installed near by user for convenience.
- 11. Installation environment
 - ①It shall be used indoor
 - ②Altitude Max. 2000m
 - ③Pollution Degree 2
 - 4 Installation Category II

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Field network device

(Q) Production stoppage models & replacement

Autonics C-88