Autonics

MOTOR DRIVER(5 PHASE MICRO STEP DRIVER) KR-55MC/KR-55M

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Thank you very much for selecting Autonics products. For your safety, please read the following before using.

Caution for your safety

*Please keep these instructions and review them before using this unit.

★Please observe the cautions that follow;

⚠ Warning Serious injury may result if instructions are not followed.

△Caution Product may be damaged, or injury may result if instructions are not followed.

*The following is an explanation of the symbols used in the operation manual. ∆ caution: Injury or danger may occur under special conditions.

1. In case of using this unit with machineries(Nuclear power control, medical equipment, vehicle, train, airplane, combustion apparatus, entertainment or safety device etc.), it requires installing fail-safe device, or contact us for information on type required.
It may result in serious damage, fire or human injury.

2. Installation, connection, operation, control, maintenance should be carried out

- by person who has been qualified.
- may cause a fire or human injury, give electronic shock 3. Please use reinforcement insulated DC power for DC type input product.
- 4. Please install this unit after considering count plan against power failure.
- It may cause human injury or damage to product by releasing holding torque o
- 5. Do not use this unit outdoors or place where there are flammable, corrosive gas, water, big vibration etc.

- water, big vioration etc.

 It may cause a fire or give electronic shock.

 6. Do not disassemble and modify this unit, when it requires, please contact us It may cause a fire or give electronic shock, damage to produc
- 7. Please install board type product with protection equipment.

- 1. Power input voltage must be used within rating specification and power line should be over than AWG NO. 18(0.75mm²). may cause a fire or give electronic shock.
- 2. Please check the connection before power.
- It may cause a fire or give electronic shock, damage to product
- 3. Please turn power off when power failure occurred.
- It may cause human injury or damage to product due to sudden movement when recove 4. Do not touch this unit during it is operating or after stopping. (Within few second)
- may cause a burn due to high temperature in surface
- 5. The emergency stop needed during operating.
- nay cause human injury or damage to produc
- 6. Please supply power after checking control input signal.
- t may cause human injury or damage to product by sudden movemen
- 7. Do not turn on the HOLD OFF signal input while it is maintaining vertical position.
- It may cause human injury or damage to product by releasing holding torque of motor.

 8. Please install a safety device when need to remain the vertical position after
- turn off the power. It may cause human injury or damage to product by releasing holding torque of motor
- 9. Please check if HOLD OFF signal input is ON when need to set the output manually.
- It may cause human injury by sudden movement.

 10. Please stop this unit when mechanical trouble occurred. It may cause a fire or human injury
- 11. Do not touch the terminal when test check pressure or insulation resistance.
- 12. Please observe rating specification.
- It may cause human injury or give electronic shock, damage to product
- 13. In cleaning the unit, do not use water or an oil-based detergent.
- It may cause a fire or give electronic shock.

 14. Please separate as industrial scrapped material when disuse this unit.

Features

- •Able to drive micro step for low vibration and noise.
- Use step angle with conversion signal.
- Obsested angle with conversion signal.
 Maximum 80 divisions, step angle of 0.72 *, controlling as accurate as down to 0.009 * It needs 40,000 pulses for 1 revolution of motor.
- •Various functions built-in, including an automatic current-down or self-diagnosis function •Realization of small, light and high speed/torque.
- •Photo coupler input insulation method to minimize the effects from external noise

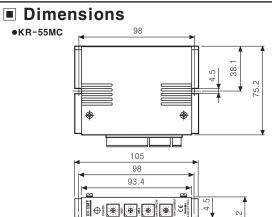
Characteristics of input pulse

- Pulse width : Min. 0.5µs •Pulse input voltage : [H]4V-8V, [L]0-0.5V Min. 0.5//s Pulse interval Input resistor : 300.Q.(CW, CCW). 390Ω (HOLD OFF
- : Max. 1 µs •Rising • Falling time DIVISION SELECTION Max. input pulse frequency: 500k pps *The above specifications are changeable without notice anytime.

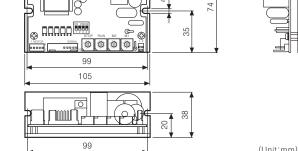
Specifications

| Model | KR-55MC | KR-55M | | | | | | |
|---------------------|--|--------------|--|--|--|--|--|--|
| Input power | 20-40VDC(Max. rating) 3A | | | | | | | |
| RUN current | 1.4A/phase max. | | | | | | | |
| Drive method | Micro step(1, 2, 4, 5, 8, 10, 16, 20, 40, 80 Division) | | | | | | | |
| Ambient temperature | 0 to 40℃ | | | | | | | |
| Ambient humidity | 35 to 85%RH | | | | | | | |
| Weight | Approx. 240g | Approx. 200g | | | | | | |
| Approval | C€ | | | | | | | |

*There is torque difference by input power

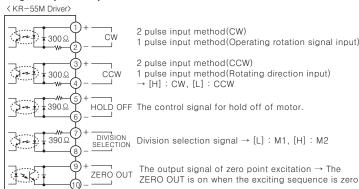


●KR-55M 99



Signal Input • Output circuit and time charts

○Signal Input • Output

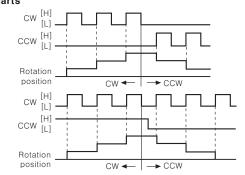


Note) If the power for driving pulse from external is over than +5V, please connect resistor

OInput • Output time charts

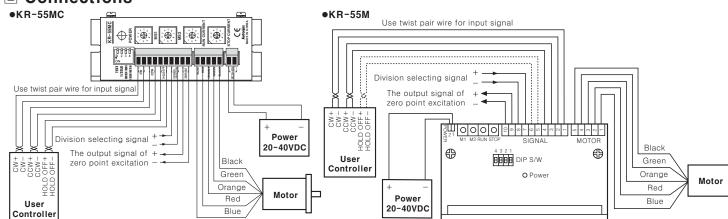
2 pulse input method

1 pulse input method

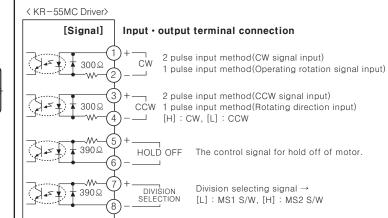


Note) When using the 2 pulse input method, do not input CW and CCW at the same time. When one of the CW and CCW signals is ON, a signal input in another directions

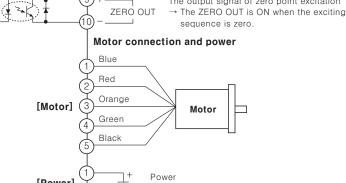
Connections



Input • Output diagram



The output signal of zero point excitation



[Power] 20-40VDC

RUN and STOP Current setting

*The run current is phase current for 5 phase stepping motor.

*Use only for less than the rated current of motor, any modification may reduce the torque.



< RUN

*When using the RUN CURRENT S/W in the range of "D to F", do not forget to first check the rated current to prevent motor heating *Increasing the run current of motor will make the torque, but motor heating may be severe. Therefore, please set run current of motor Which is appropriate to the load

| S/W NO | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | Α | В | С | D | Е | F |
|------------|-----|------|------|------|------|------|------|------|-----|------|------|-----|-----|------|------|-----|
| Current(A) | 0.5 | 0.58 | 0.66 | 0.75 | 0.81 | 0.88 | 0.96 | 1.03 | 1.1 | 1.15 | 1.25 | 1.3 | 1.4 | 1.47 | 1.53 | 1.6 |
| | | | | | | | | | | | | | | | | |

< STOP CURRENT>

Holding torque[kaf • cm]

*Using the STOP CURRENT S/W is allowed, and the set value is a percentage of the setting value of RUN CURRENT S/W.

Ex)In the case of using run current as 1.4A/phase, set the S/W to "5", reduces 50% and sets the stop current as 0.7A/phase. *This function is work at only HOLD OFF signal is [L].

When it is [H], the current for phase will be cut off, so CURRENT DOWN will not work

Holding torque[kgf • cm] × Stop current[A]

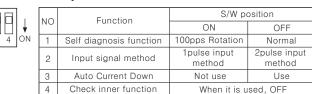
(The stop current is applied to motor) = Rated current of motor[A] S/W NO 0 1 2 3 4 5 6 7 8 9 A B C D E % 27 31 36 40 45 50 54 58 62 66 70 74 78 82 86 90

Division setting

| Division | 1 | 2 | 4 | 5 | 8 | 10 | 20 | 40 | 80 | 16 | |
|----------|----------|----------|---|---------|-------|---------|---------|--------|------------------|----|---|
| MS1 (M1) | MS (M | S2 2) | 5 | ō Phase | motor | rotatio | n angle | = Step | angle Divisio | |) |

- *Operates the selective division with MS1 S/W on the selection signal [L] and MS2 S/W on the selection signal [H] according to the division selecting signal.
- ★Enables the adjustment of division during stepping motor operation(Rotation) and allows a double Micro-Step operation with the division selecting signal. *The Zero point excitation signal is ON when the excitation sequence is 0.
- In the case of a 5 phase motor with 0.72° with an output every 7.2°, changing the step angle after turning on the power might not produce any output

Function S/W



Caution for using

1. Caution for signal input

(i)When using the 2 pulse input method, do not input CW and CCW at the same time. When one of the CW and CCW signals is [H], a signal input in another directions may not work normally.

@Current of input power maximum current.

3 Please use enough power enables to supply for motor driving.

2. Caution for wiring

①Use Twist pair(Over than 0.2mm²) for the signal wire should be shorter than 2m. ②Please use over than AWG No.18(0.75mm²) wire for motor wiring (when it needs to extend) and power line

3 Please check the polarity of power before driving it.

Caution for installation
 Please mount a heating panel on metal surface closely.

②Please mount this product at well-ventilated place in order to increase the heating efficiency of heating panel.

4. Function S/W

①The self-diagnosis is outputting a pulse of 100pps while the position of S/W is ON, which is setting to test the motor and driver.

(2) Check the position of self-diagnosis S/W before turn on the power. If turn on the power at the state of ON, It could be dangerous due to abrupt motor starting. 3The Auto Current Down reduces the run current at a constant rate to minimize heating when stop the motor

. Installation environment

1 It shall be used indoor

②Altitude Max 2000m ③Pollution Degree 2

(4) Installation Category II

*It may cause malfunction if above instructions are not followed.

Main products

■ COUNTER ■ TIMER

■ TEMPERATURE CONTROLLER

■ PANEL METER
■ TACHOMETER/LINE SPEED METER /PULSE METER

■ DISPLAY LINIT

■ PROXIMITY SENSOR

■ PHOTOFI FCTRIC SENSOR

■ FIBER OPTIC SENSOR

■ PRESSURE SENSOR

■ ROTARY ENCODER

& CONTROLLER

SENSOR CONTROLLER ■ POWER CONTROLLER ■ STEPPING MOTOR & DRIVER

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