

∅ 50mm Shaft Absolute Type

Diameter ∅ 50mm Shaft type Absolute Rotary encoder

■ Features

- Compact size of external diameter 50mm
- Various output code: BCD, Binary, Gray Code (Customizable)
- Various and high resolution (720, 1024 divisions)
- IP 64 (Partial waterproof, Oil proof)

■ Applications

Precision machine tool, Fabric machinery, Robot, Parking system

 Please read "Caution for your safety" in operation manual before using.



■ Ordering information

EP50S	8	–	1024	–	1	–	R	–	P	–	24
Series	Inside		Pulse/1 Revolution		Output code		Revolution direction		Control output		Power supply
Diameter ∅ 50mm shaft type	∅ 8mm		Refer to revsolutions		1 : BCD Code 2 : Binary Code 3 : Gray Code		F : Output value increase at CW direction R : Output value increase at CCW direction		P : PNP open collector output N : NPN open collector output		5 : 5VDC ±5% 24 : 12–24VDC ±5%

* Gray code is customizable.

■ Specifications

Item		Diameter ∅ 50mm shaft type of Absolute rotary encoder	
Resolution		(Note1)	*6, *8, *12, *16, *24, *32, *40, 45, 60, 64, 90, 128, 180, 256, 360, 512, 720, 1024
Electrical specification	Output code/Output angle	Refer to "Output waveform"	
	Control output	PNP open collector output	Output voltage : Min. (Power supply–1.5)VDC, Load current : Max. 32mA
		NPN open collector output	Load current : Max. 32mA, Residual voltage : Max. 1VDC
	Response time (Rise/Fall)	Ton=800nsec, Toff=Max. 800nsec (Cable length: 2m, I sink=32mA)	
	Max. Response frequency	35kHz	
	Power supply	• 5VDC ±5% (Ripple P–P : Max. 5%) • 12–24VDC ±5% (Ripple P–P : Max. 5%)	
	Current consumption	Max. 100mA (disconnection of the load)	
	Insulation resistance	Min. 100MΩ (at 500VDC mega between all terminals and case)	
	Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)	
	Connection	Cable outgoing type (Cable gland)	
Mechanical specification	Starting torque	Max. 40gf • cm (0.004N • m)	
	Rotor inertia	Max. 40g • cm ² (4 × 10 ^{–6} kg • m ²)	
	Shaft loading	Radial : 10kgf, Thrust : 2.5kgf	
	Max. allowable revolution	(Note2)	3000rpm
Vibration		1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours	
Shock		Max. 50G	
Ambient temperature		–10 ~ 70℃ (at non-freezing status), Storage: –25 ~ 85℃	
Ambient humidity		35~85%RH, Storage: 35~90%RH	
Protection		IP64 (IEC standard)	
Cable		∅ 7mm, 15P, Length : 2m, Shield cable	
Accessory		Fixing bracket, Coupling	
Unit weight		Approx. 380g	
Approval		CE	

※ (Note1) "*" Marked division in resolution is being developed. Not indicated type is customizable.

※ (Note2) Max. allowable revolution ≥ Max. response revolution $\left[\text{Max. response revolution (rpm)} = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec} \right]$

(A)
Counter

(B)
Timer

(C)
Temp.
controller

(D)
Power
controller

(E)
Panel
meter

(F)
Tacho/
Speed/
Pulse
meter

(G)
Display
unit

(H)
Sensor
controller

(I)
Switching
power
supply

(J)
Proximity
sensor

(K)
Photo
electric
sensor

(L)
Pressure
sensor

(M)
Rotary
encoder

(N)
Stepping
motor &
Driver &
Controller

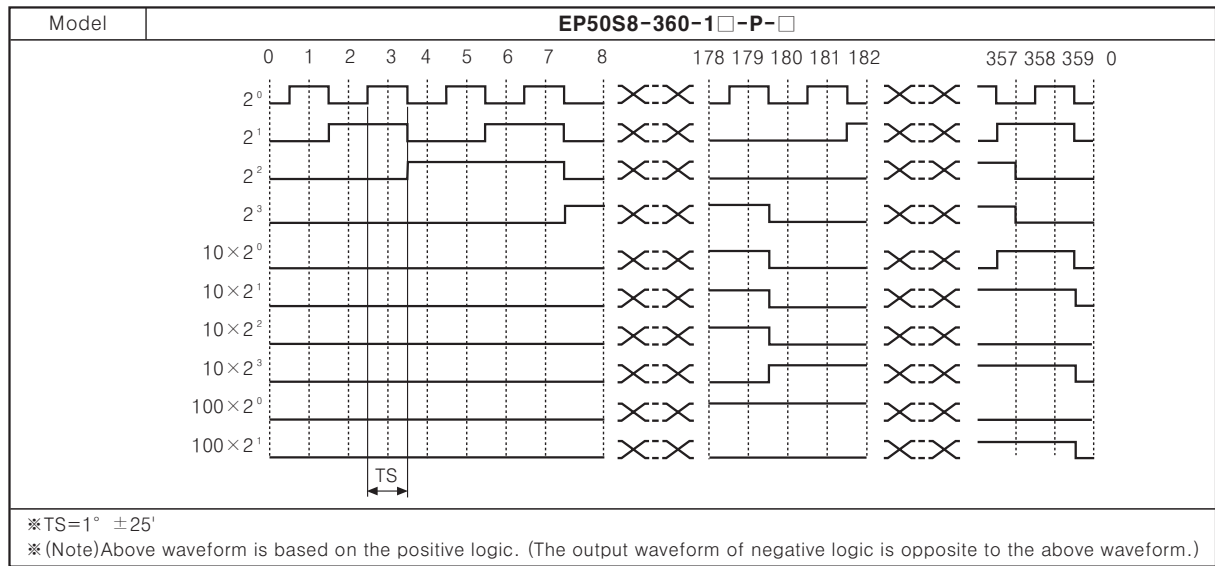
(O)
Graphic
panel

(P)
Production
stoppage
models &
replacement

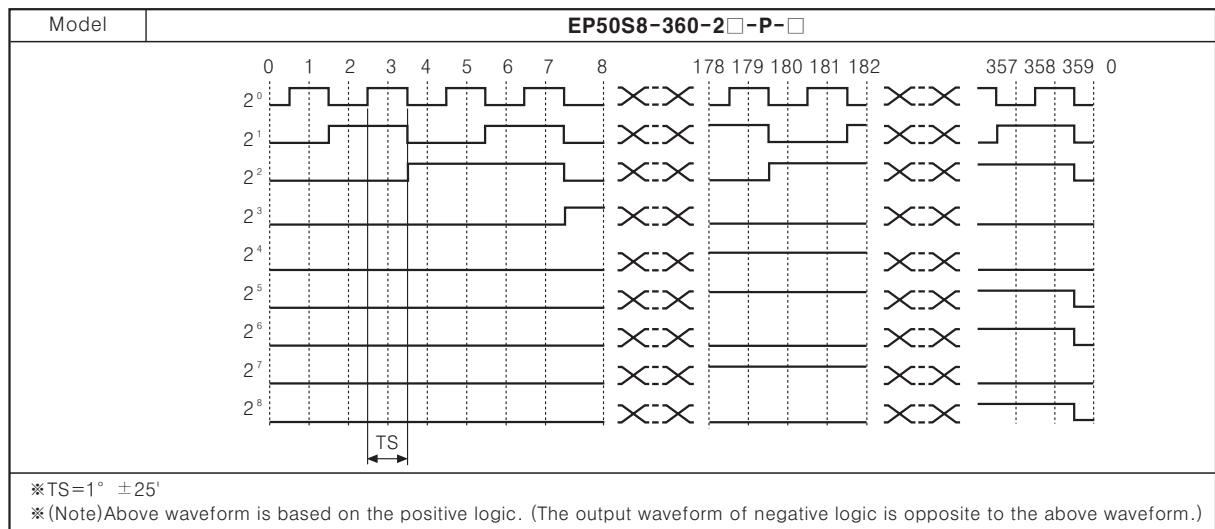
EP50S Series

■ Output waveform

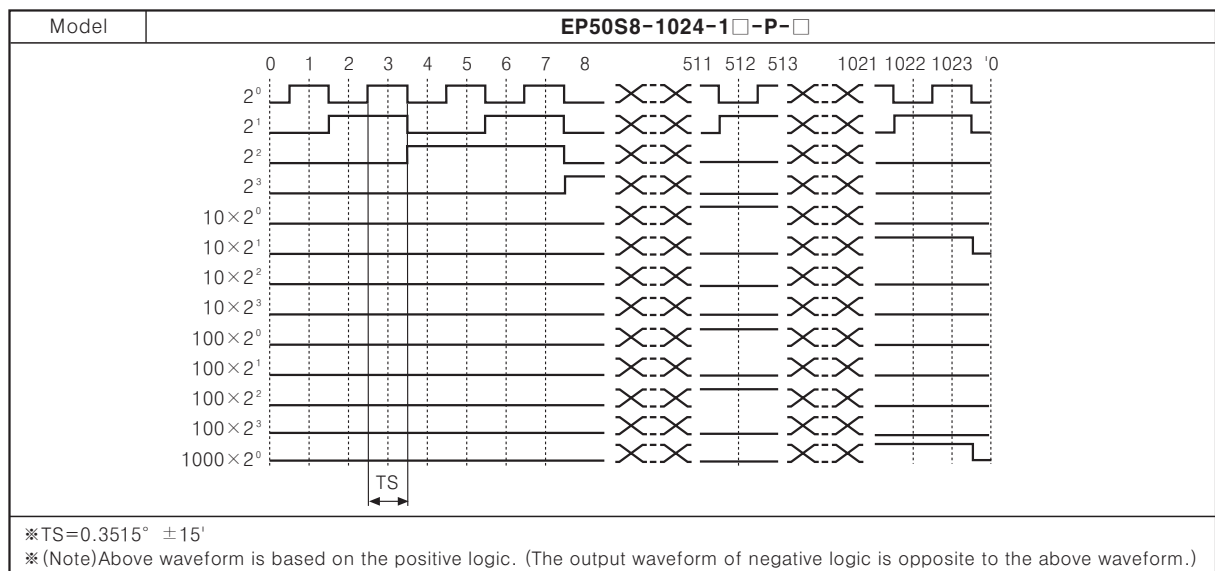
● 360 division (BCD CODE output)



● 360 division (BINARY CODE output)



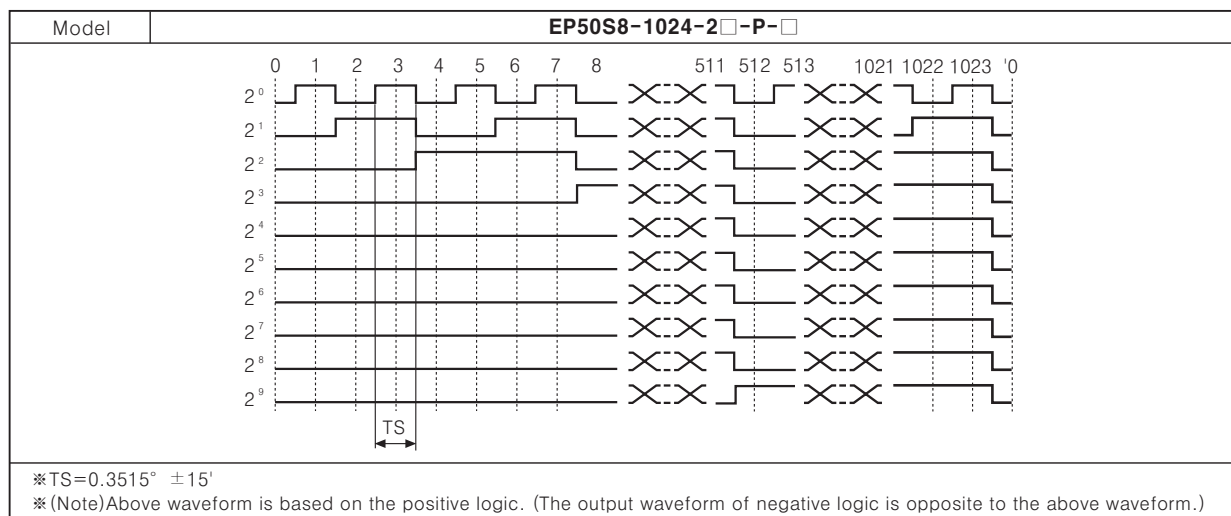
● 1024 division (BCD CODE output)



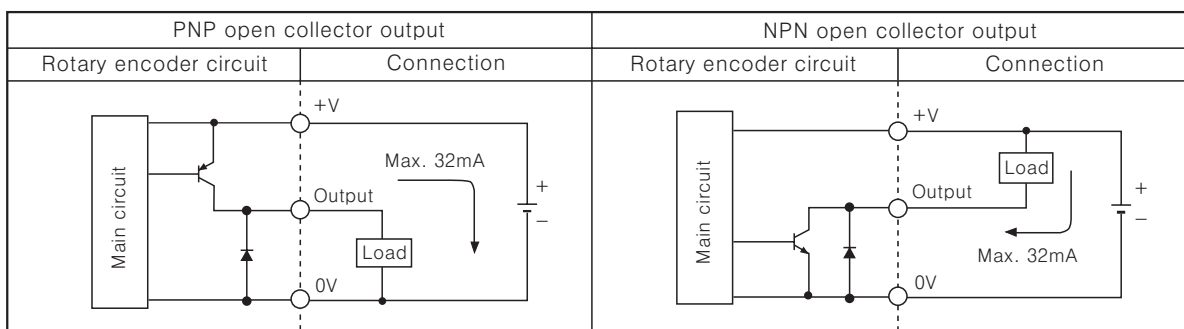
∅ 50mm Shaft Absolute Type

Output waveform

1024 division (BINARY CODE output)



Control output diagram



※Output circuit of all phases is same.

Connections

BCD Code

Resolution	6	8	12	16	24	32	40	45	60	64	90	128	180	256	360	512	720	1024	
Color	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	
Power	White	+V																	
	Black	GND(0V)																	
Output	Brown	TP1	TP1	TP1	TP1	TP1	TP1	TP1	2°	2°	2°	2°	2°	2°	2°	2°	2°	2°	
	Red	TP2	TP2	TP2	TP2	TP2	TP2	TP2	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹	
	Orange	2°	2°	2°	2°	2°	2°	2°	2²	2²	2²	2²	2²	2²	2²	2²	2²	2²	
	Yellow	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2³	2³	2³	2³	2³	2³	2³	2³	2³	2³	
	Blue	2²	2²	2²	2²	2²	2²	2²	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	
	Purple	EP		2³	2³	2³	2³	2³	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	(2¹×10)	
	Gray	NC		(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2°×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	(2²×10)	
	White/Brown	NC		EP	EP	(2¹×10)	(2¹×10)	(2¹×10)	NC			(2³×10)	(2³×10)	(2³×10)	(2³×10)	(2³×10)	(2³×10)	(2³×10)	
	White/Red	NC				EP	EP	EP	NC				(2°×100)	(2°×100)	(2°×100)	(2°×100)	(2°×100)	(2°×100)	
	White/Orange	NC													(2¹×100)	(2¹×100)	(2¹×100)	(2¹×100)	(2¹×100)
	White/Yellow	NC															(2²×100)	(2²×100)	(2²×100)
	White/Blue	NC																	(2³×100)
	White/Purple	NC																	(2°×1000)
	Shielded wire	F.G																	

■ Connections

- Binary code

Resolution		6	8	12	16	24	32	40	45	60	64	90	128	180	256	360	512	720	1024
Color		division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division	division
Power	White	+V																	
	Black	GND(0V)																	
Output	Brown	TP1	TP1	TP1	TP1	TP1	TP1	TP1	2°	2°	2°	2°	2°	2°	2°	2°	2°	2°	2°
	Red	TP2	TP2	TP2	TP2	TP2	TP2	TP2	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2¹
	Orange	2°	2°	2°	2°	2°	2°	2°	2²	2²	2²	2²	2²	2²	2²	2²	2²	2²	2²
	Yellow	2¹	2¹	2¹	2¹	2¹	2¹	2¹	2³	2³	2³	2³	2³	2³	2³	2³	2³	2³	2³
	Blue	2²	2²	2²	2²	2²	2²	2²	2⁴	2⁴	2⁴	2⁴	2⁴	2⁴	2⁴	2⁴	2⁴	2⁴	2⁴
	Purple	EP	EP	2³	2³	2³	2³	2³	2⁵	2⁵	2⁵	2⁵	2⁵	2⁵	2⁵	2⁵	2⁵	2⁵	2⁵
	Gray	NC		EP	EP	2⁴	2⁴	2⁴	NC			2⁶	2⁶	2⁶	2⁶	2⁶	2⁶	2⁶	2⁶
	White/Brown	NC				EP	EP	2⁵	NC				2⁷	2⁷	2⁷	2⁷	2⁷	2⁷	2⁷
	White/Red	NC						EP	NC						2⁸	2⁸	2⁸	2⁸	2⁸
	White/Orange	NC																2⁹	2⁹
	White/Yellow	NC																	
	White/Blue	NC																	
	White/Purple	NC																	
	Shiled wire	F.G																	

※Unused wires must be insulated.

※The metal case and shield wire of encoder should be grounded(F.G).

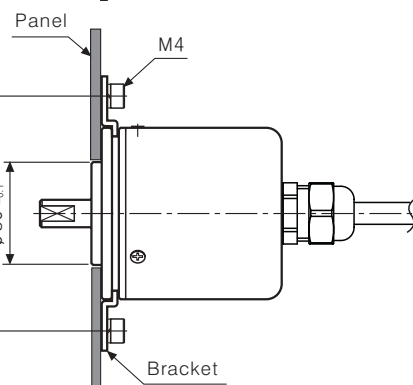
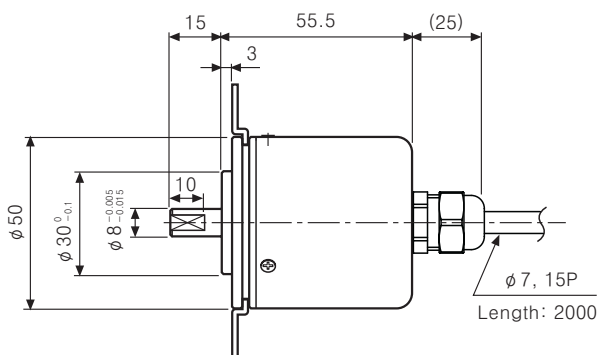
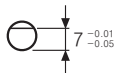
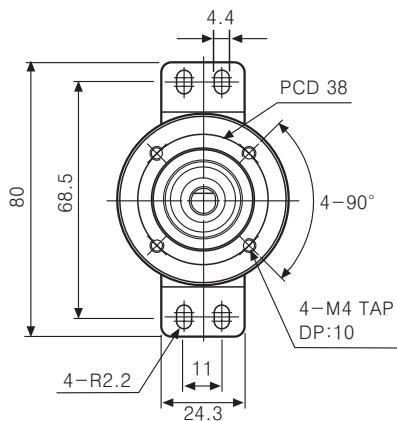
※NC : Not Connected.

※TP1/TP2 : It is an enablement signal to decide signal recognition for output easily because, output signal cycle is long in low resolution model.

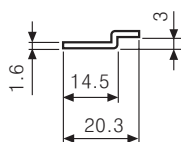
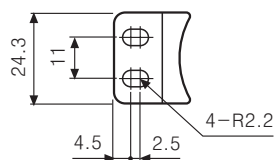
※Ep : It is a parity signal to be outputted as odd number of parity.

※Output cable must not be short-circuited, because Driver IC is used in output circuit.

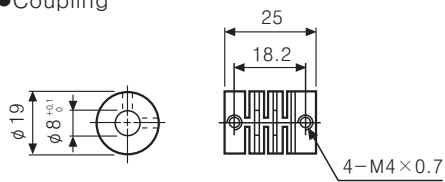
▣ Dimensions



- Bracket



- Coupling



(Unit:mm)