



EAM PARALLEL-SSI MULTITURN ABSOLUTE ENCODER



Absolute multiturn PARALLEL encoder description

This series is designed for application where a very high precision is required, even also on extended linear distances. Resolutions up to 13 bits on the single turn (8,192 ppr) and 14 bits as number of turns (16,384 turns) are available. Sturdy mechanic parts and several flanges make this series suitable in such a wide range of applications assuring high performances even in the most tough industrial applications. This series is available with cable or connector output both with Gray or binary code. The PUSH PULL electronic is suitable for all industrial application fields.

Absolute multiturn SSI encoder description

The absolute multiturn encoder series with SSI output provides data with the same format as previously described for singleturn encoders. Considering the high data volume in multiturn encoders, the serial data transfer is an efficient solution in order to curb the number of wires and the SSI standard is a valuable one.

The output data is a 25 bit word and useful bits are proportional to the resolution chosen for the encoder.

This transmission standard efficiently reduces wiring issues maintaining the highest level of performances. Similarly to singleturn encoders, number of wires for the transmission is 4 (2 for the data and 2 for the clock signal –both are transmitted in differential logic). A wide range of mechanical parts and flanges designed to satisfy different requirements is available.

SSI encoder ordering code

Full stop to separate special versions

EAM 63 A 4096 / 4096 G 5 S X X 10 X 3 MC R . XXX

Absolute multiturn encoder **EAM**

Body dimension **58**
Body dimension **63**
Body dimension **90**
Body dimension **115**

Type of flange
mod. EAM63/90/115 **A**
mod. EAM58 **B**
mod. EAM58 **C**
mod. EAM63 **D**
mod. EAM63 **E**
mod. EAM58/63 **F**
mod. EAM63 **G**

Turns
2/4/8/16/32/64/128/256
512/1024/2048/4096/
8192*/16384*

*Please directly contact our offices for more than 25 bit coding availability

Resolution
2/4/8/16/32/64/128/256/512
1024/2048/4096/8192

Code type
Binary **B**
Gray (Standard) **G**

Input voltage
5
8 ÷ 28

Output types
SSI (Serial Synchronous Interface) **S**
For optional about output types please refer to the absolute output section

Logic
To be reported if not used **X**

Special version code numbered from 001 to 999

R Radial
A Axial

PC 12 poles with 1,5 m standard output cable
MC MS type 7 poles connector
HA H type 12 poles connector

R.P.M.
3 3000 with IP66
6 6000

Enclosure rating
X IP54
S Optional IP66 with the exception of EAM63G/F

Shaft diameter
6 ø 6g6 mm - 58B
8 ø 8g6 mm - 58B - 63A/D/E - 90A
9 ø 9,52g6 mm - 63A/D/E - 90A
10 ø 10g6 mm - 58B/C - 63A/D/E - 90A - 115A
11 ø 11g6 mm - 115A

Bore diameter only for mod. 58F - 63F/G
8 ø 8H7 mm
9 ø 9,52H7 mm
10 ø 10H7mm
12 ø 12H7 mm
14 ø 14H7 mm
15 ø 15H7 mm

Options
X To be reported if not used
ZE Electronic zeroing
ZP Push-button zeroing

Multiturn ABSOLUTE ENCODERS

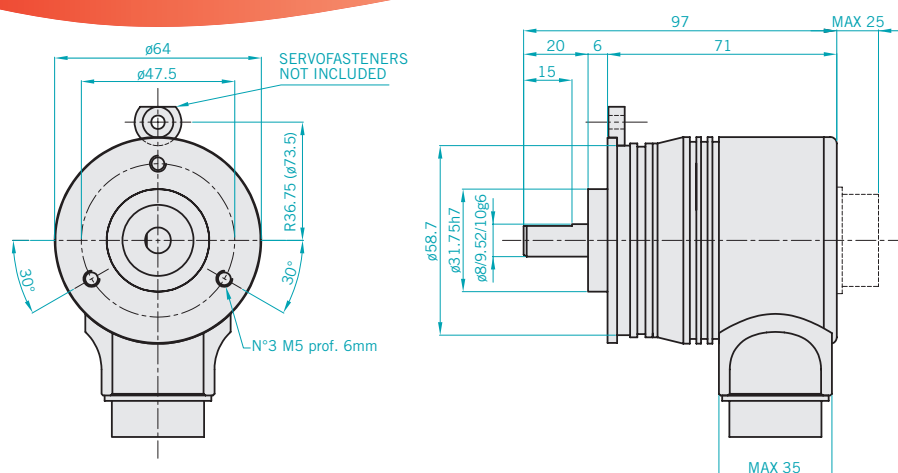
EAM PARALLEL-SSI

Output connections for SSI

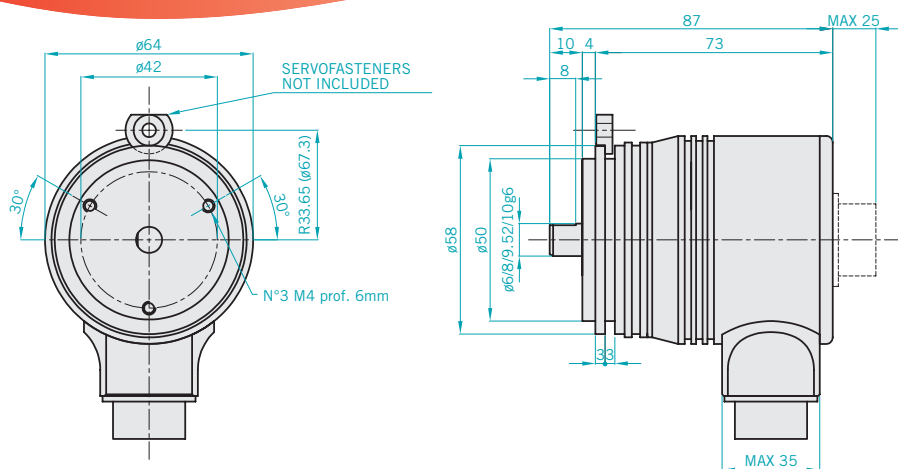
FUNCTION	12 WIRE CABLE COLOURS	PIN M07MP	PIN H12
+ Vdc	red	G	8
0 Volt	black	F	1
U/D	red/blue	E	5
Data +	green	C	2
Data -	brown	D	10
Clock +	yellow	A	3
Clock -	orange	B	11
ZE	white	/	4



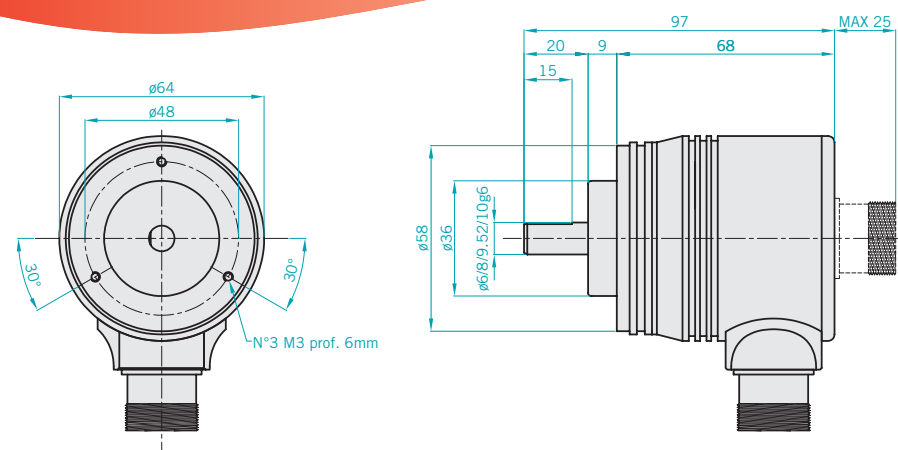
EAM63 A



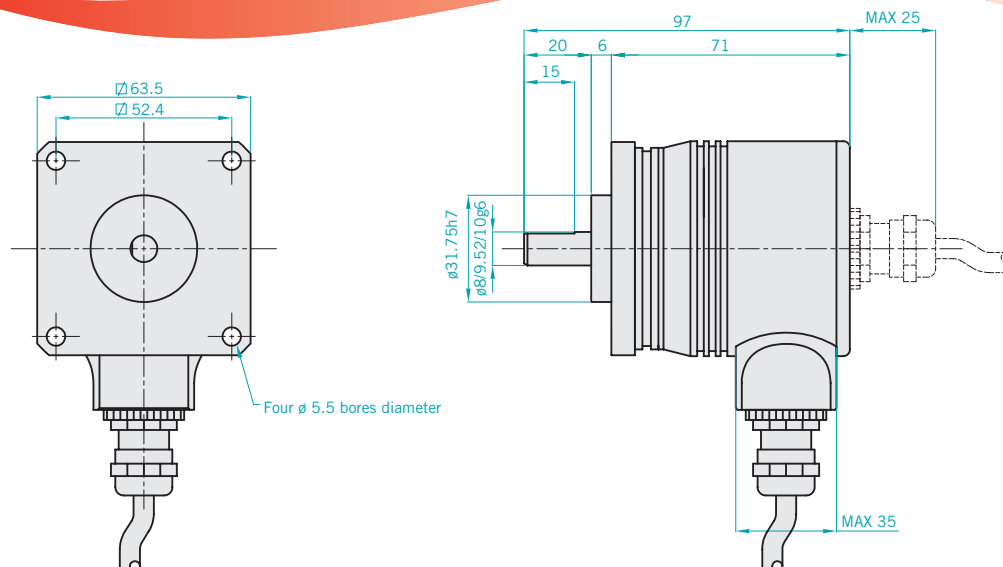
EAM58 B



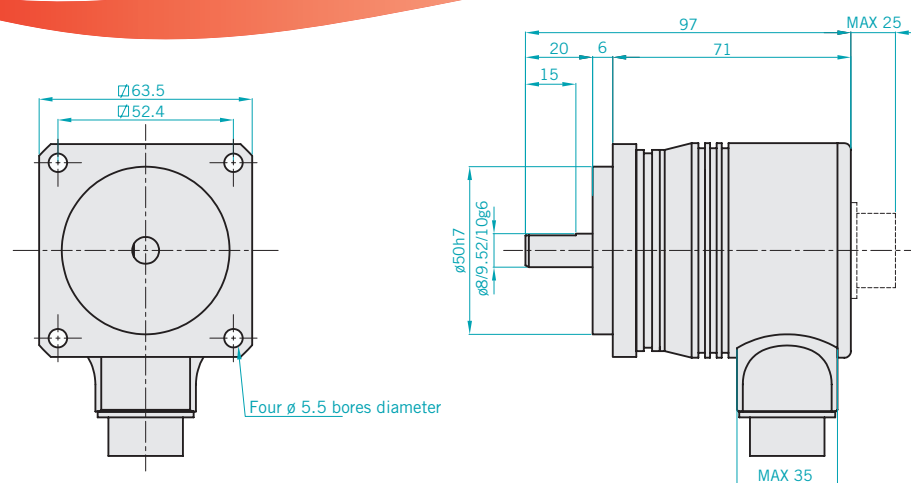
EAM58 C



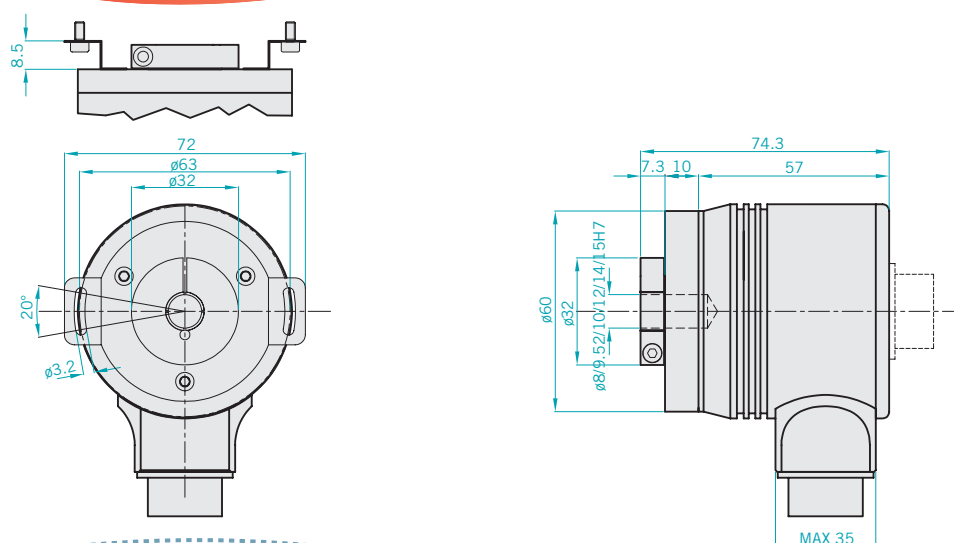
EAM63 D



EAM63 E



EAM58 F



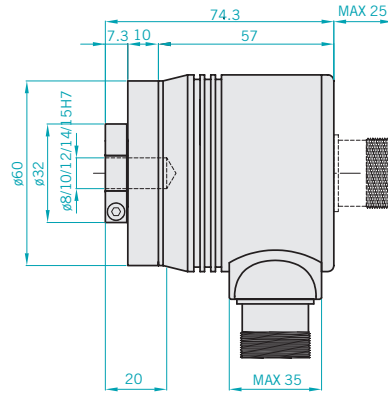
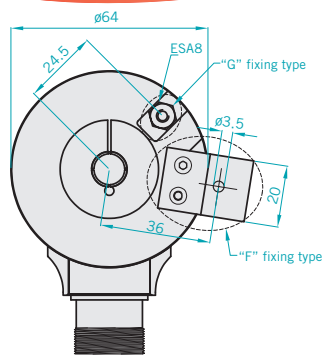
Multiturn ABSOLUTE ENCODERS

EAM PARALLEL-SSI

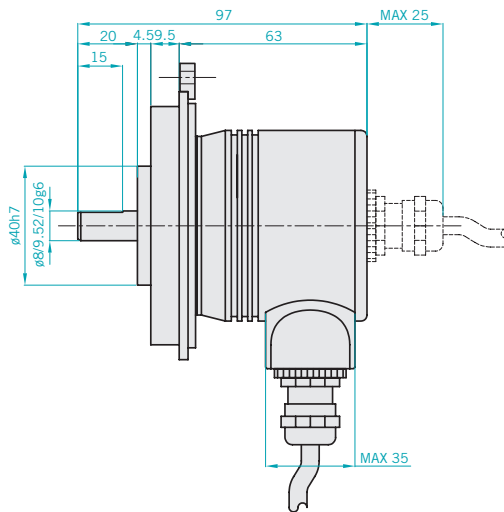
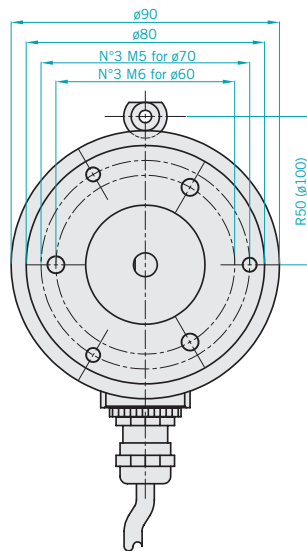




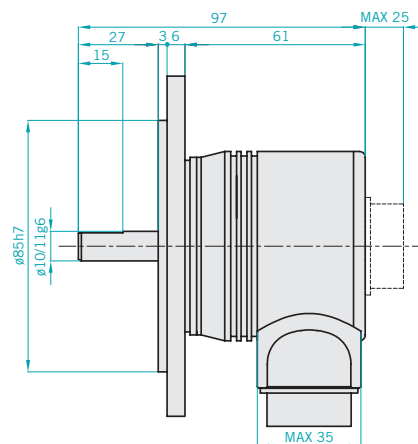
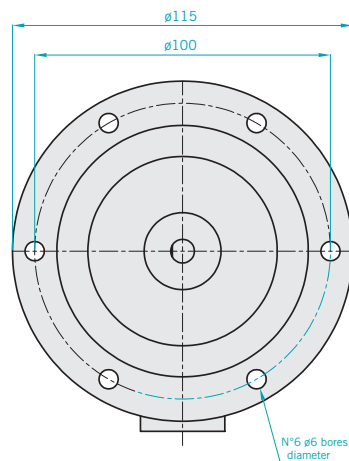
EAM63 F - EAM63 G



EAM90 A



EAM115 A

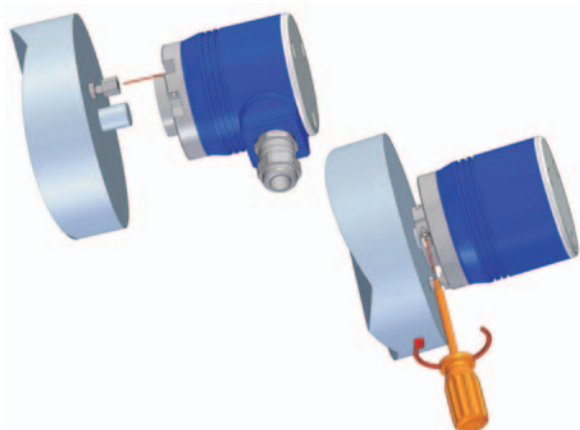


Multiturn ABSOLUTE ENCODERS

EAM PARALLEL-SSI

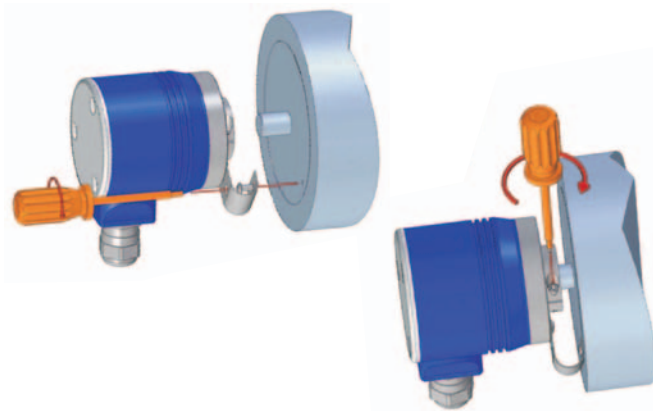
HOW TO MOUNT THE EAM63G

- 1) Fix the antirotation pin on the motor flange.
- 2) Couple the encoder shaft with the motor shaft, ensuring that the pin is inserted on the frontal part of the encoder (maintaining a minimum distance of 0,5 mm).
- 3) Fix the encoder shaft by the metal ring.



HOW TO MOUNT THE EAM63F

- 1) Couple the encoder shaft with the motor shaft.
- 2) Fix the spring at the motor flanges without screwing it.
- 3) Fix the encoder shaft by the metal gear.
- 4) Block the spring.



Mechanical specifications

Shaft diameter (mm)	ø6 g6 - 58B ø8 g6 - 58B - 63A/D/E - 90A ø9,52 g6 - 63A/D/E - 90A ø10 g6 - 58B - 63A/D/E - 90A - 11A ø11 g6 - 11A
Bore diameter (mm)	ø8 H7- 58F - 63F/G ø9 H7- 58F - 63F/G ø10 H7- 58F - 63F/G ø12 H7- 58F - 63F/G ø14 H7- 58F - 63F/G ø15 H7- 58F - 63F/G
R.P.M. Max	6000 continuous 3000 continuous for 63G 3000 with IP66
MAX shaft load	10 N (1 Kp) axial with ø6 shaft 20 N (2 Kp) radial with ø6 shaft 100 N (10 Kp) axial 100 N (10 Kp) radial
Shock	50 G for 11 msec
Vibrations	10G 10 ÷ 2000 Hz
Bearings life	10 ⁹ revolutions
Bearings	n° 2 ball bearings
Shaft material	Stainless steel AISI303
Body material	Aluminium UNI 9002/5 - (D11S)
Housing material	Aluminium alloy 6060
Flange material	Aluminium UNI 9002/5 (D11S)
Weight	350 g -58B/C -63A/D/E/G 750 g - 90A -115A

Environmental specifications

Enclosure rating	IP54 IP66 optional -58B/C -63A/D/E -90A
Operating temperature	0° ÷ +60°C
Input current with no output load	-15° ÷ +70°C

PARALLEL electrical specifications

Turns	2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 512 / 1024 / 2048 / 4096 / 8192 16384
PPR	2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 512 / 1024 / 2048 / 4096 / 8192
Input voltage	8 ÷ 28 Vdc
Input current with no output load	100 mA
Source and sink current	20 mA for channel
Output types	PUSH PULL (Positive logic)
Output frequency	200 KHz output code $F = \frac{\text{RPM} \times \text{Resolution}}{60}$
Accuracy	+/- 1/2 LSB

SSI electrical specifications

Turns	2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 512 / 1024 / 2048 / 4096 / 8192 16384
PPR	2 / 4 / 8 / 16 / 32 / 64 / 128 / 256 512 / 1024 / 2048 / 4096 / 8192
Input voltage	5 Vdc / 8 ÷ 28 Vdc
Input current with no output load	100 mA
Output types	SSI (Serial Synchronous Interface)
Monostable time	10 - 25 us
Time between two clock sequences	> 35 us
Frequency range	100 KHz - 1 MHz
Accuracy	+/- 1/2 LSB