123456

= 123458

DIN W48×H48mm, W72×H36mm, W72×H72mm counter/timer

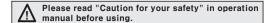
Upgraded functions

123458

a: 123458

Upgrade

- Available to set 6 digits (0.00001 to 999999) prescale value (4 Digit: 0.001 to 9999)
- •Built-in Modbus communication function (Communication model)
- Available to set the One-Shot output time in 10ms. (0.01sec. to 99.99sec.)
- •Increase contact capacity to 5A(CTS, CTM Series)
- Available to set Count Start Point. (Initial value)
- Improved to select memory protection function in the indicator
- •Added BATCH counter function (CTM Sereis)
- ●Added Counter Up-1 / Up-2 / Down-1 / Down-2 input modes
- Added Counter TOTAL / HOLD operation modes in the indicator
- Added Timer TOTAL / HOLD / On Time Display operation modes in the indicator
- Added Timer INT2 / NFD / NFD.1 / INTG output modes
- Added Timer range 999.999s / 9999m59 / 99999.9h





Integrated device management program(DAQMaster)

- •DAQMaster is a integrated device management program for convenient management of parameters and multiple device data monitoring.
- •Visit our website (www.autonics.com) to download user manual and integrated device management program.

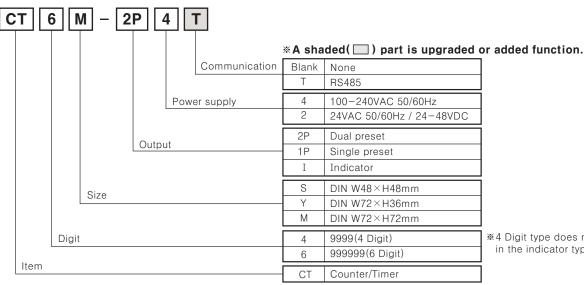
Computer specification for using software >

Item	Recommended specification
Processor	IBM PC compatible computer with Intel Pentium III or above
Operating system	Windows 98 / NT / XP / Vista / 7
RAM	Over 256MB
Hard disk	Over 1GB of available space
VGA	Over 1024×768
Communication port	RS232 Serial port, USB port

⟨ DAQMaster screen >



Ordering information



***4** Digit type does not exist in the indicator type.

(A) Photo electric

(B) Fiber optic sensor

Door/Area

Proximity sensor

Pressure sensor

(F) Rotary encoder

(G) Connector/

Temp controlle

Socket

SSR/ Power controlle

(J) Counter

(K) Timer

Panel meter (M)

Tacho/

Speed/ Pulse meter (N) Display

unit (0) Sensor

controlle

Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

Production stoppage models & replacement

■Specifications

Series			C1	'S	СТҮ	СТМ
Digit	oligit 4 6 6 6		6			
		Dual Preset	CT4S−2P□□	CT6S−2P□□	CT6Y−2P□□	CT6M−2P□□
Mod	lel	Single Preset	CT4S−1P□□	CT6S−1P□□	CT6Y−1P□□	CT6M−1P□□
		Indicator	-	CT6S−I□□	CT6Y−I□□	CT6M−I□□
Dig	it	Count value	11mm	10mm	10mm	13mm
Size		Preset value	8mm	7mm	7mm	9mm
Pow	er	AC Power			100-240VAC 50/60Hz	
Supp	oly [AC/DC Power		2	4VAC 50/60Hz / 24-48VDC	
		voltage range	90 to 110% of rated voltage(AC Power type)			
Pow	ım —	AC Power	Max. 12VA			
ptic		AC/DC Power			C: Max. 10VA / DC: Max. 8W	
		nting speed		Selectable	1cps, 30cps, 1kcps, 5kcps, or 10	kcps
		Counter		Reset	input : Selectable 1ms or 20ms	
sigr wic		Timer			ctable 1ms or 20ms	INA, INB, RESET, INHIBIT, BATCH RESET: Selectable 1ms or 20ms
Input			Selectabl -Voltage	e voltage input or N e input : input imped	lo-voltage input lance is 5.4kΩ, 'H' level : 5-30Vl	DC, 'L' level : 0-2VDC
					cuit impedance : Max. 1kΩ, Residual	
One-		t output			Selectable 0.01s to 99.99s	
	Without com.	Contact output	Dual preset : Si Single preset :		Dual preset : SPST(1a Single preset : SPDT(a) 1EA, SPDT(1c) 1EA 1c) 1EA
Ħ	Solid state output			Dual preset: 1NP Single preset: 1N	PN open collector NPN open collector	Dual preset:3NPN open collector Single preset:2NPN open collector
outpı	Com.	Contact output	Dual preset : SPST(1a)2EA Single preset : SPDT(1c)1EA		SPST(1a)2EA SPDT(1c)1EA	Dual preset: SPST(1a), SPDT(1c) Single preset: SPDT(1c)
Control output	ŏ	Solid state output	_		Dual preset: -	Dual preset: 2NPN open collector Single preset: 2NPN open collector
ပိ	city	Contact output	250VAC 5A resistive load		250VAC 3A resistive load	250VAC 5A resistive load
	Capacity	Solid state output			30VDC Max. 100mA Max.	
Exteri	nal s	ensor power	12VDC ±10%, 100mA Max.			
Memo	ory re	etention	10years(When using non-volatile semiconductor memory type)			
Timer	acc	uracy	Repeat error, Set e	Repeat error, Set error, voltage error, Temperature error - Power ON Start: Max. ±0.01% ±0.05 se - Signal Start: Max. ±0.01% ±0.03 sec.		
Insula	ation	resistance		Min. 100MΩ (500VDC Megger)		
Diele	ctric	strength		2,0	000VAC 50/60Hz for 1minute	
Noise (AC F			±	2kV the square way	ve noise(pulse width:1 μ s) by the r	noise simulator
Vibra	tion	Mechanical	0.75mm a	mplitude at frequen	cy of 10 to 55Hz in each of X, Y,	Z directions for 1 hour
Vibra	ιιοιι	Malfunction	0.5mm amp	litude at frequency	of 10 to 55Hz in each of X, Y, Z d	irections for 10 minutes
Sho	ck	Mechanical		300m/s² (A ₁	pprox. 30G) 3 times at X, Y, Z dir	ection
3110		Malfunction		100m/s ² (A ₁	oprox. 10G) 3 times at X, Y, Z direction	
Relay		Mechanical			Min. 10,000,000 times	
		Electrical	Min. 100,000 times			
Prote					IP65 (Front panel only)	
		emperature		-10 to 55°	C, Storage temperature: -25 to (65℃
		numidity			RH, Storage humidity: 35 to 85%	
Appro		,			(€ : %) us	
<u> </u>		nt	Approx	159g	Approx. 149g	Approx. 253g
Unit weight		11	7 1 ppi 0 2	1008	Tippion, ITUS	11pprox. 200g

■Communication specification

Protocol	Modbus RTU(16bit CRC)	
Connection method	RS485	
Application standard	Compliance with EIA RS485	
Number of connections	31, it is available to set address 1 to 127	
Communication method	Half Duplex	
Synchronous method	Asynchronous	
Communication distance	within max. 800meter	
Communication speed	speed 2,400/4,800/9,600/19,200/38,400bps(Factory default: 9,600bps)	
Response waiting time	5 to 99ms(Factory default : 20ms)	
Start bit	1bit (Fixed)	
Data bit	8bits (Fixed)	
Parity bit	None, Even, Odd(Factory default : None)	
Stop bit	1, 2bit(Factory default: 2bit)	

J-7 Autonics

Connections

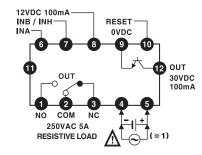
OCT S-2P

12VDC 100mA
INB / INH
INA
6 7 3 9 10

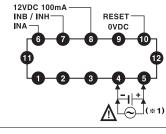
OUT2
30VDC
100mA

OUT1
250VAC 5A
RESISTIVE
RESISTIVE
RESISTIVE
(* 1)

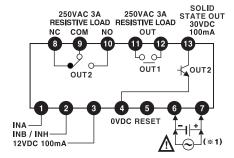
©CT□S-1P□



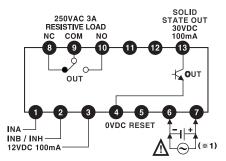
©CT6S-I□



©CT6Y-2P□



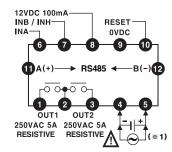
©CT6Y-1P□



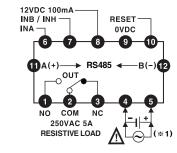
(***1**)Source

-AC Power: 100-240VAC 50/60Hz -AC/DC Power: 24-48VDC, 24VAC 50/60Hz Be careful that connections are different between communication model and non-communication model when wiring.

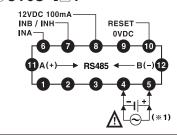
©CT□S-2P□T



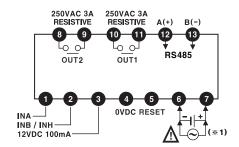
©CT□S-1P□T



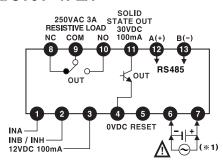
©CT6S-I□T



©CT6Y-2P□T



©CT6Y-1P□T



***2)**INHIBIT Signal

- -Counter operation: If INHIBIT signal is applied, count input will be prohibited.
- -Timer operation: If INHIBIT signal is applied, time progressing will stop.(HOLD)

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

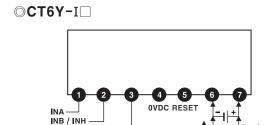
(Q) Stepping motor & Driver & Controller

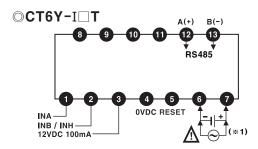
(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

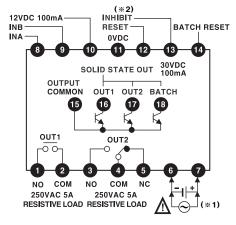
Be careful that connections are different between communication model and non-communication model when wiring.



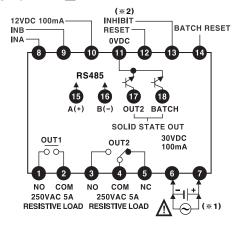




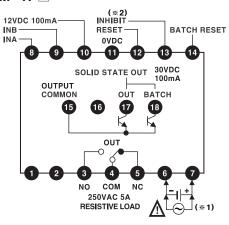
12VDC 100mA



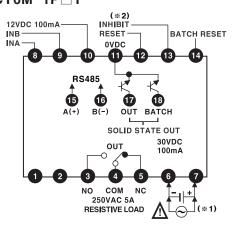




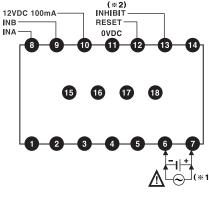
©CT6M-1P□



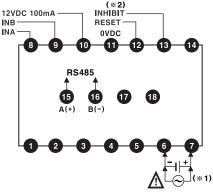
©CT6M-1P□T



©CT6M-I□



©CT6M-I□T



(***1**)Source

- -AC Power: 100-240VAC 50/60Hz
- -AC/DC Power: 24-48VDC, 24VAC 50/60Hz

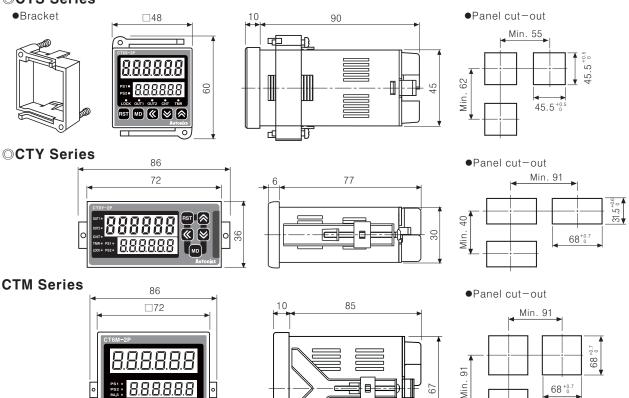
(*2)INHIBIT Signal

- -Counter operation: If INHIBIT signal is applied, count input will be prohibited.
- -Timer operation: If INHIBIT signal is applied, time progressing will stop. (HOLD)

J-9 Autonics

Dimensions

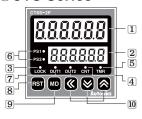
OCTS Series



■Front panel identification

RST BA MD (🗸 🙈

OCTS Series



OCTY Series



Model	Changed	Notice	
CT6Y-1P		- .	
CT6S-1P	PS2→PS	There are no PS1, OUT1	
CT4S-1P	OUT2→OUT	I FDs	١.
CT6M-1P		LLD3.	יו
CT6Y-I		There are no	
CT6S-I	PS2→PS	PS1, OUT1	
CT6M-I		OUT2 LEDs.	
			•

1 Count indicator(Red LED) -Run mode

- : Count mode-Indicates count value.
- Timer mode-Indicates time progressing.
- -Function setting mode
- : Indicates function setting mode.

*The indicator type does not exist in

2 Preset value indicator (Yellow-Green LED)

- -Run mode: Indicates preset value.
- -Function setting mode: Indicates setting value1.
- 3 Key Lock: Lights when setting key lock.
- 4 The operation of counter indicator
- 5 The operation of timer indicator
 - TMR LED flashes when the timer is operating.
 - TMR LED lights when the operating time stops.

6 Check preset value and display change of it

PS1 LED lights when checking or changing the setting value1. PS2 LED lights when checking or changing the setting value2.

7 Output(OUT1, OUT2) indicator

OUT1 lights when output1 is on. OUT2 lights when output2 is on.

8 Reset kev

By pressing key in Run mode, the count value is initialized and output is returned. By pressing so key in BATCH counter mode, BATCH count value resets

OCTM Series



68 +0.7

(Unit:mm)

9 Mode kev

- By pressing key for 3sec (parameter setting)/5sec (communication) in RUN mode, it moves to function setting mode.
- By pressing we key in function setting mode, select function setting mode. By pressing key over 3 sec., it moves to Run mode.
- By pressing we key over 1 sec. in function setting checking mode, it moves to Run mode.

10 Set key

- C: To enter into setting value (PS1, PS2) change status and shift digit of setting value (PS1, PS2).
- : To decrease setting value in setting value change mode, change setting value in function setting mode, move down checked value in function setting check mode.
- To increase setting value in setting value change mode, change setting value in function setting mode, move up checked value in function setting check mode. By pressing key over 1 sec. in Run mode, enters into function setting check mode.

11 BATCH key

- By pressing key in run mode to enter into BATCH counter indication mode.
- BATCH output indicator(Red LED)
- BATCH setting value checking and changing indicator (Yellow-Green LED)

Lights when checking and changing BATCH setting value.

Photo electric sensor

(B) Fiber sensor

Door/Area

(D) Proximity sensor

Pressure

Rotary encoder

Connector/ Socket

Temp controlle

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

Tacho Speed Pulse meter

(N) Display unit

Sensor controller

Switching power supply

(Q) Stepping motor & Driver & Controlle

(R) Graphic/ Logic panel

(S) Field network device

Production

stoppage models & replacement

Sensor

(NPN output)

Input connections

Brown

Black

Blue

Solid-state input(Standard sensor: NPN output type sensor)

Counter/Timer

CT Series

≤5.4kΩ

+12V

Inner circuit

of input part

Counter/Timer Counter/Timer Sensor CT Series CT Series Brown +12V +12V $5.4k\Omega$ **≤**5.4kΩ Black $(\times 2)$ Inner circuit Inner circuit of input part of input part Blue 0V (NPN open collector output)

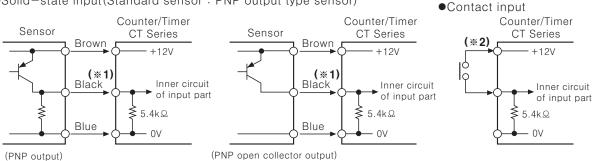
Contact input

(*1)INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

(***2)**Counting speed: 1 or 30cps setting(Counter)

OVoltage input(PNP)

Solid-state input (Standard sensor : PNP output type sensor)

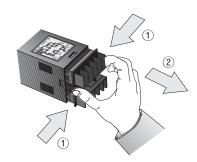


(*1)INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

(***2)**Counting speed: 1 or 30cps setting(Counter)

Input logic Selection[No-voltage input(NPN)/Voltage input(PNP)]

- 1. The power must be cut off.
- Detach the case from the body. (CTS, CTY Series)

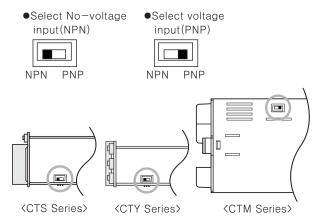


*Case detachment

Squeeze toward 1 and pull toward 2 as shown in picture.

A Please check if the power is cut off.

3. Select input logic by using input logic switch(SW1) inside Counter/Timer.



- 4. Push a case in the opposite direction of 2-2.
- 5. Then apply the power to Counter/Timer.

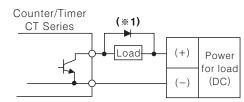
J-11 Autonics

■Output connections

Counter/Timer
CT Series

(Power of load)

*Use proper load not to exceed the capacity.



**Use proper load and power for load not to excess ON/OFF capacity(30VDC Max. 100mA max.) of solid state output.

*Be sure not to apply reverse polarity of power.

(**1)When use inductive load(Relay etc), surge absorber (Diode, varistor etc) must be connected between both sides of the load.

■ Factory default

	Parameter	Factory default
	Input mode (/ n)	Up/Down-C (Ud-[)
	Output mode (all E.ā.)	F (F)
	CPS (EP5)	30cps (30)
	Indication mode (indicator type)(d5P.ñ)	TOTAL (EDERL)
	OUT2 (aUE2)	100ms (100)
	OUT1 (aUE I)	Hold (Hata)
ē	Decimal point (dP)	
Counter	Min. reset time (-5L)	20ms (20)
00	Input logic (51 6)	NPN (¬P¬)
	Prescale decimal point (5[.dP)	6Digit type:, 4Digit type:
	Prescale value (5£L)	6Digit type: 1.00000, 4Digit type: 1.000
	Start Point setting (5£r£)	00000
	Counting memory (dALA)	Clear (ELr)
	Lock key (LoCY)	Lock off (L.oFF)
	Preset value 1 (PS1)	1000 (1000)
	Preset value 2 (PS2)	5000 (5000)
	Time range (Hall-/āl n/5EE)	6Digit type: 0.001s-999.999s, 4Digit type: 0.001s-9.999s
	Up/Down mode (U-d)	Up (UP)
	Indication mode(Indicator type) (d5P.ā)	TOTAL (EDERL)
	Memory protection(Indicator type) (dRER)	CLEAR ([Lr)
	Output mode (all E.ā)	OND (and)
Timer	OUT2 output time (aUE2)	Hold (Hald)
<u>⊔</u>	OUT1 output time (all L I)	100ms (IDD)
'	Input logic (5! 6)	NPN(nPn)
	Input signal time (I n.E)	20ms (20)
	Lock key (LoCt)	Lock off (L.oFF)
	Preset value 1 (PS1)	1000 (1000)
	Preset value 2 (PS2)	5000 (5000)
L	Communication address (Addr)	01 (00 !)
Communication	Communication speed (6P5)	9600bps (95)
)ič	Communication parity (Prty)	NONE (none)
l m	Communication stop bit (5EP)	2 (2)
Ē	Response waiting time (-54)	20ms (20)
ပိ	Communication writing (E = Ā.º)	Enable (EnA)

■Error display

Error display	Errors	Output status	How to return
PS1 O FRI L	Failed in data loading for exsiting setting values	OFF	Power on again

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(⋈)

Tacho/ Speed/ Pulse meter

Display unit

(O) Sensor controller

(P) Switching power supply

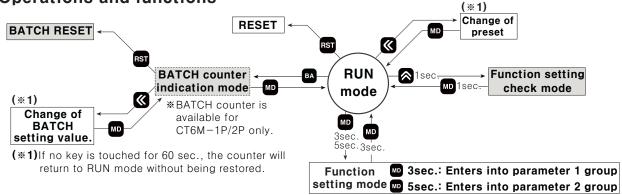
(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

■Operations and functions



Change of preset(Counter/Timer)

•Even if changing the preset value, input operation and output control will continue. In addition, the preset value could be set to 0 and 0 preset value turns ON. According to output mode, preset value could not be set to 0. (When setting to 0, preset value "0" will flash 3 times.)



In Run mode, it enters into the preset value setting mode using & key. 'PS1' LED lights and first digit of preset value flashes.



The preset value is set to '180' using (), (a) and (b) keys, then press (a) key to enter into the PS2 setting mode.



The preset value is set to '200' using ℳ, ℳ and ℳ keys, then press ᢍ key to complete PS2 setting and return to Run mode.

*Press key to save set value after changing the setting value. Then, it moves to next parameter or returns to RUN mode. However, if no key is touched for 60 sec., it will return to RUN mode without being saved.

OFunction setting check mode

• Setting value of function setting mode can be confirmed using the ⋒ and ❷ keys.

Switching display function in preset indicator

•Setting value 1(PS1) and setting value 2(PS2) are displayed each time pressing we key in dual preset model. (In timer, it is available for and, and I, or and 2 output mode.)

○Reset

•In Run mode or function setting mode, if pressing so key or applying the signal to the RESET terminal on the back side, present value will be initialized and output will maintain off status.

■BATCH Counter(For CT6M-1P□□/CT6M-2P□□ model only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

OChange of BATCH setting value

If pressing A key in Run mode, it will enter into BATCH counter indication mode.

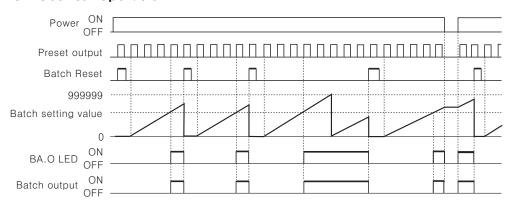


It enters into setting value change mode using & key.
(BA.S lights, first digit of setting value flashes.)



BATCH value is set to '200' using () and () keys, then press () key to complete BATCH setting value and move to BATCH counter indication mode

©BATCH Counter operation



OBATCH Counting operation

•BATCH counting value is increasing until BATCH resest signal applied. BATCH counting value will be circulated when it is over 999999.

1)BATCH counting operation in Counter : Counts the number of reaching setting value of CT6M-1P \square or reaching dual setting value of CT6M-2P \square

2) BATCH counting operation in Timer: Counts the number of reaching setting time.

(In case of "FLL" output mode, count the number of reaching T.off setting time and T.on setting time.)

OBATCH output

- •If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- •If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- •When the power is cut off then resupplied in status of BATCH output is ON, BATCH ouput maintains ON status until BATCH reset signal is applied.

OBATCH reset input

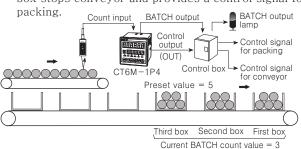
- •If pressing reset button or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset.
- •When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.

Application of BATCH Counter function

Counter

In case, put 5 products in a box then pack the boxes when they reaches to 200.

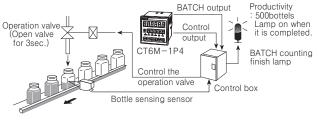
- © Counter preset setting value="5", BATCH setting value="200"
- When the count value of counter reaches to the preset value "5", the control output (OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to "200", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for



Timer

Fills milk into the bottle for 3sec. (setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on.

(Setting time: 3sec., BATCH setting value: 500)



(A) Photo electric sensor

(B) Fiber optic

> (C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

Panel meter

(L)

Tacho/ Speed/ Pulse meter

unit

(O) Sensor controller

(P) Switching power supply

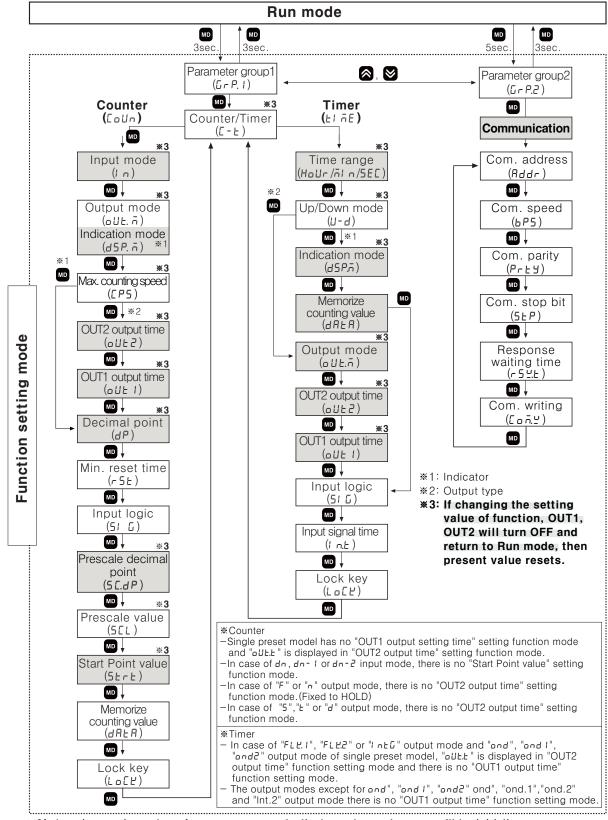
(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

■Flow chart for function setting mode



- *If changing setting value of parameter group1, display value and output will be initialize.
- *Press key over 3sec./5sec. in RUN mode to enter into parameter 1 group/ parameter 2 group.

 Press key over 3 sec. in function setting mode to return RUN mode.
- *Input operation and output control can be set in function setting mode.
- ※If changing set value of
 ※3 marked parameters in function setting mode, OUT1 and OUT2 output will be turned OFF and then the current value is reset.
- *Parameter 2 group is not available to non-communication models.

J-15 Autonics

■Parameter setting(Counter)

Satting made		How to set
Setting mode Counter/Timer		* [alla: COUNTER
(E-E)	CoUn ←→ ŁI ñE	EI ñE: TIMER
Input mode (In)	Ud-[←→ UP ←→ UP- 1 ←→ UP- 2 ←→ dn ←→ dr	n-! ←→ dn-2 ←→ Ud-A ←→ Ud-b
Output mode	● "UP", "UP-1", "UP-2" or "dn", "dn-1", "dn F → n → E → r → ピ → P → 9 → t	R .
(oUŁ.ñ)	*In case that output mode is "F", "n", the (Fixed to HOLD)	ere is no "OUT2 output time" setting mode.
Indication mode	● "Ud-A", "Ud-b", "Ud-[" input mode F ↔ n ↔ [↔ r ↔ ½ ↔ P ↔ 9 ↔ \$	**If output mode is set to "d" when ma counting speed is set to 5Kcps, 10Kcp max. counting speed is automatically set to 30cps. (Factory default setting
(d5 P.ñ)	HoLd ←→ ŁoŁAL ※It is added that	ndicator, indicate mode selection(d5P.ā) is displayed. the function which can set the preset value when . (Refer to J-20page ' ©Counter operation of the indicator
Max. counting speed (EP5)	30 ↔ 12 ↔ 52 ↔ 102 ↔ 1	 *Counting speed is that of one by one(1:1) duty ratio of INA or INB input signal, and it is applied in INA and INB at the same time. *In case of setting "d" in output mode, you can choose 1 cps, 30 cps, or 1kcps.
OUT2 output time (oUt 2)	C: To shift flashing digit position of OUT2 output time value.☑ A: To change OUT2 output time value.	 *Set OUT2 one-shot output time. *Setting range: 0.01 to 99.99 sec. *It does not appear if F or n output mode is selected.
OUT1 output time	S: To shift flashing digit position of OUT1output time value.	*Set OUT1 one-shot setting time *Time range: 0.01 to 99.99 sec Hold
(oUE 1)	❷❷: To change OUT1 output time value.	★ HoLd is displayed by pressing key 4 times.
*1 Decimal point (dP)	•6Digit type •4Digit type ***	Setting the decimal point is applied same
	<u>†</u>	to counting value and setting value.
Min. reset time (r 5 L)	/ → 20 Unit: ms	to counting value and setting value. the min. external RESET signal width.
time	αPα: No−Voltage input	<u> </u>
time (r5E) Input logic (SIE) *1 Prescale	nPn: No-Voltage input PnP: Voltage input •6Digit type	the min. external RESET signal width.
time (r5E) Input logic (51 G)	nPn: No-Voltage input PnP: Voltage input ●6Digit type	the min. external RESET signal width. eck input logic value(PNP, NPN).
time (r5E) Input logic (5I E) **1 Prescale decimal point	nPn: No-Voltage input PnP: Voltage input •6Digit type	the min. external RESET signal width. eck input logic value(PNP, NPN). *Prescale decimal point position is not set
time (r5L) Input logic (5! L) **1 Prescale decimal point (5L.dP) Prescale value	nPn: No-Voltage input PnP: Voltage input ●6Digit type ◆4Digit type ◆ ■4Digit type ◆ ■4Digit type	*Prescale decimal point position is not set below the decimal point setting digits(dP). *Setting range of prescale value 6Digit type: 0.00001 to 99999.9 4Digit type: 0.001 to 9999.9
time (r5t) Input logic (51 5) **1 Prescale decimal point (5C.dP) Prescale value (5Ct) Start Point Value		**Prescale decimal point position is not set below the decimal point setting digits(dP). **Setting range of prescale value 6Digit type: 0.00001 to 99999.9 4Digit type: 0.001 to 999.9 **Refer to 5. Prescale function. **Setting range of Start Point value (Connected with decimal point setting) 6Digit type: 0.0000 to 999999 4Digit type: 0.0000 to 999999 4Digit type: 0.0000 to 99999
time (r5t) Input logic (5! 5) **1 Prescale decimal point (55.dP) Prescale value (55.t) Start Point Value (55.t) Memory protection	#Che PnP: Voltage input ●6Digit type ◆4Digit type ◆2: To shift the flashing digit. ※A: To change the prescale value. ②: To shift the flashing digit. ②: To change the Start Point value.	**Refer to 5. Prescale function. **Setting range of Start Point value (Connected with decimal point setting) 6. Digit type: 0.00001 to 999.9 **Refer to 5. Prescale function. **Setting range of Start Point value (Connected with decimal point setting) 6. Digit type: 0.00000 to 999999 **Refer to 6. Start Point value (Connected with decimal point setting) 6. Digit type: 0.00000 to 999999 **Refer to 6. Start Point function. **ELr: Initializes count value when power is off. **FE: Memorizes count value at the moment of power off
time (r5t) Input logic (5t f) **1 Prescale decimal point (5f.dP) Prescale value (5ft) Start Point Value (5trt) Memory protection (dRtR)	#Che PnP: No-Voltage input	the min. external RESET signal width. eck input logic value(PNP, NPN). **Prescale decimal point position is not set below the decimal point setting digits(dP). **Setting range of prescale value 6Digit type: 0.00001 to 99999.9 4Digit type: 0.001 to 999.9 **Refer to 5. Prescale function. **Setting range of Start Point value (Connected with decimal point setting) 6Digit type: 0.00000 to 99999 4Digit type: 0.0000 to 99999 **Refer to 6. Start Point function. **ELr: Initializes count value when power is off. rEE: Memorizes count value at the moment of power off
time (r5t) Input logic (51 L) **1 Prescale decimal point (5L.dP) Prescale value (5LL) Start Point Value (5Lrt) Memory protection (dALA)	#Che PnP: Voltage input ●6Digit type ◆4Digit type ◆2: To shift the flashing digit. ※A: To change the prescale value. ②: To shift the flashing digit. ②: To change the Start Point value.	**Refer to 5. Prescale function. **Setting range of Start Point value (Connected with decimal point setting) 6. Digit type: 0.00001 to 999.9 **Refer to 5. Prescale function. **Setting range of Start Point value (Connected with decimal point setting) 6. Digit type: 0.00000 to 999999 **Refer to 6. Start Point value (Connected with decimal point setting) 6. Digit type: 0.00000 to 999999 **Refer to 6. Start Point function. **ELr: Initializes count value when power is off. **FE: Memorizes count value at the moment of power off

*1) Explanation of decimal point and prescale decimal point setting

-Decimal point setting: Set decimal point of the display value on front indicator.

Autonics J-16

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller (R) Graphic/

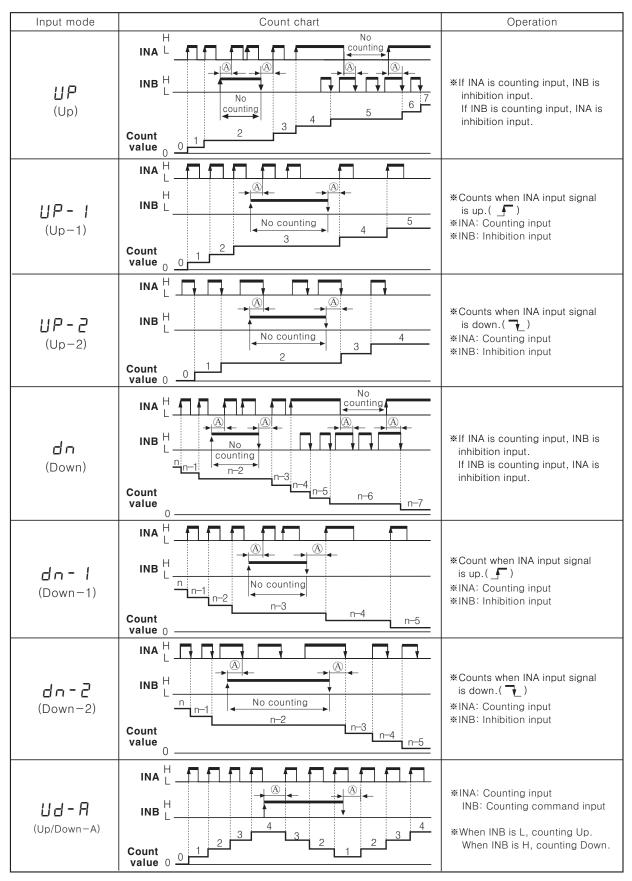
Logic panel

Field network device

(T) Production stoppage models & replacement

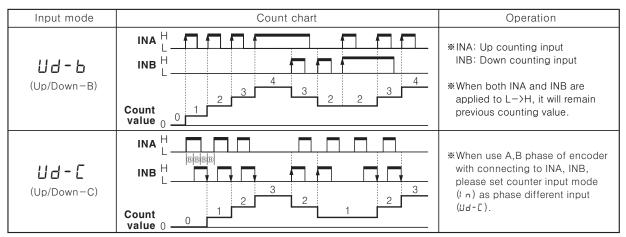
⁻Prescale decimal point setting : Set prescale decimal point of counting regardless of decimal point of display value on front indicator.

■Input operation mode(Counter)



J-17 Autonics

■Input operation mode(Counter)



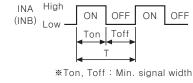
 \divideontimes a signal width should be over min. signal width and b signal width should be over a half min. signal width. If not, ± 1 will occur.

*The meaning of "H" and "L"

	Voltage input (NPN)	No-Voltage input (PNP)
Н	5-30VDC	Short circuit
L	0-2VDC	Open

፠Min. signa	l width by	counting	speed
-------------	------------	----------	-------

Counting speed	Min. signal width
1cps	500ms
30cps	16.7ms
1kcps	0.5ms
5kcps	0.1ms
10kcps	0.05ms

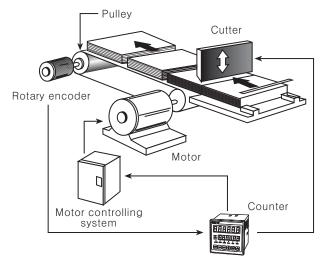


■Prescale function(Counter)

This function is to set and indicate calculated unit for actual length, liquid measure, position etc. It is called "Prescale value" for measured length, measured liquid, measured position, etc per 1 pulse.

For example, P is the number of pulses per 1 revolution of a rotary encoder and L is the desired length to be measured. Prescale value is [the desired length (L)]/[the number of pulses (P) per 1 revolution of the rotary encoder.]. It is the length per 1 pulse of a rotary encoder.

Ex)Control length by the counter and the rotary encoder



[In case of 22mm diameter(D) of Pulley connected with the encoder of 1,000 pulse]

•Prescale value = $\frac{\pi \times \text{Diameter of the pully(D)}}{\text{The number of pulses per 1 revolution of the encoder}}$ $= \frac{3.1416 \times 22}{1000}$ = 0.069 mm/pulse

To control conveyor position in 0.1mm, set the decimal point to tenth place (-----) in decimal point setting mode (dP) and set the prescale decimal point to thousandth place (----) in prescale decimal point setting mode (5LdP). Then set prescale value "0.069" in prescale setting mode (5LdP).

■Start point function(Counter)

This function is that start point value works as initial value when on counting mode.

- •In case of "dn", "dn-1" or "dn-2" in timer input mode, it is not available.
- •When reset is applied, the present value is initialized to start point.
- ullet After count up in " \mathcal{E} ", " \mathcal{F} " or " \mathcal{F} " output mode, preset value starts at start point value.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

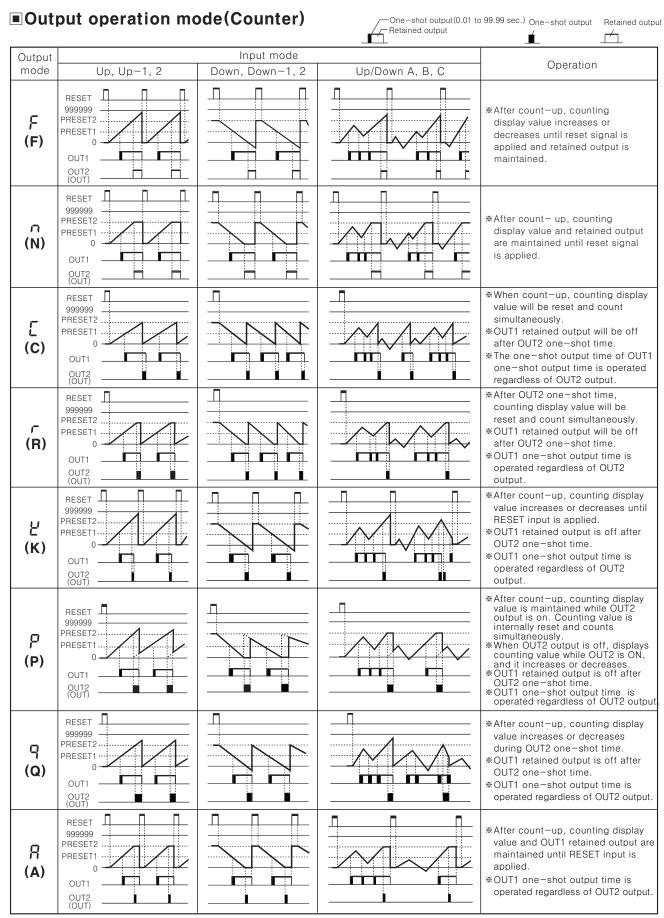
(P) Switching power supply

(Q) Stepping motor & Driver & Controller

Graphic/ Logic panel

Field network device

(T) Production stoppage models & replacement



*The single preset type output (OUT) is operated as OUT2 of dual preset type.

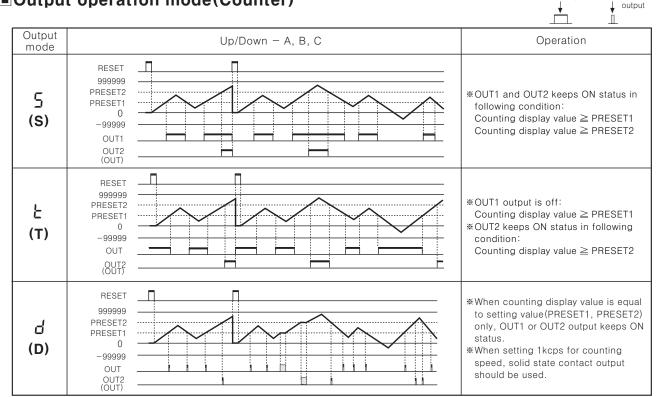
J-19 Autonics

^{*}OUT1 output could be set to 0 in all modes and 0 value output turns ON.

^{*}OUT2 output could not set to 0 in C([), R(r), P(P) or Q(9) output mode.

Retained output

■Output operation mode(Counter)

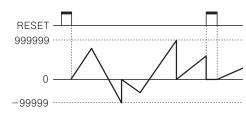


- ★The single preset type output(OUT) is operated as OUT2 of dual preset type.
- *The dual preset model OUT1 output is operated as one−shot or retained output.(except 5 (S), Ł (T) or J (D) output mode)
- *OUT1 output could be set to 0 in all modes and 0 value output turns ON.
- *OUT2 output could not set to 0 in C(E), R(F), P(P) or Q(9) output mode.

■Counter operation of the indicator(CT6S-I, CT6Y-I, CT6M-I)

Indicate	Count	chart	
mode (d5P.5)	In case of input mode is Up (Up, Up-1, Up-2)	In case of input mode is Down (Down, Down-1, Down-2)	Operation
E o E A L (TOTAL)	999999 0	RESET 999999 0 -99999	Count value increases or decreases until RESET input is applied. When reaching max. count value or min. count value, it will be reset and count simultaneously.
Hold (HOLD)	RESET 999999 PRESET 0	RESET 999999 PRESET 0	Count value increases or decreases until RESET input is applied, count value indicator flashes when reaching preset value(Up count) or 0(Down count).

●In case of the input mode is Command input(Ud-A), Individual input(Ud-b), Phase difference input(Ud-E),



※In case of UP/DOWN(Ud-A, Ud-b, Ud-E) input mode, indication mode(d5Pā) of the configuration is not displayed. (A) Photo electric sensor

Coincidence

(B) Fiber optic sensor

(C) Door/Area

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary

Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

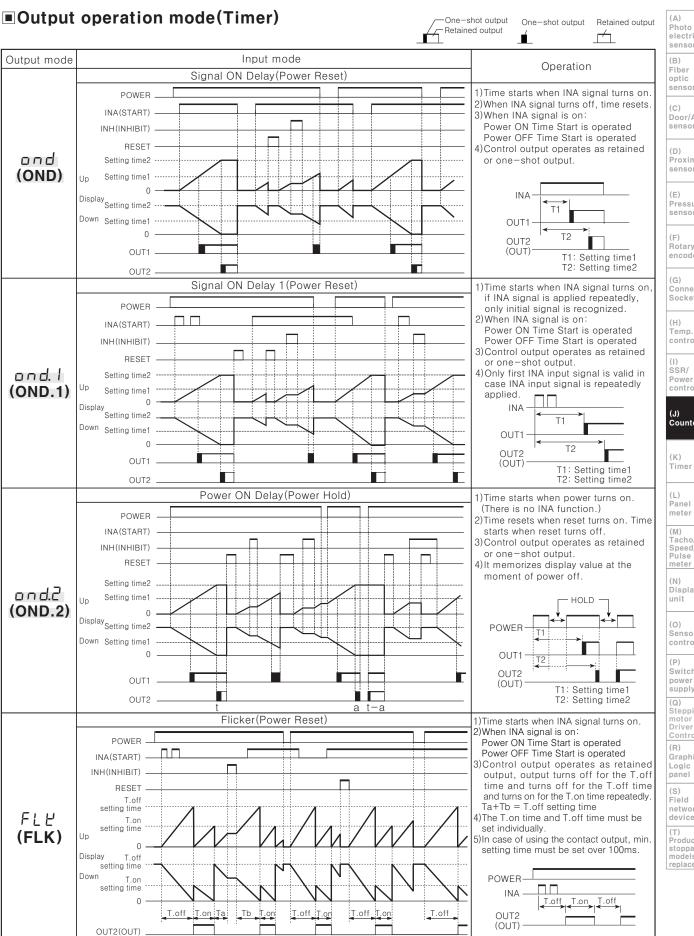
(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

Parameter setting(Timer) (w key: To select setting mode, ♥ or ♠ key: To change setting value) Setting mode How to set Counter/Timer **※** [□Un: COUNTER Follo ← → Fl ōF (E-E)LI ñE: TIMER ●6Digit type SEC 5 E C SEC 5 E C 999.999 9999.99 999999 999999 9959.99 0.01s to 0.01s to 0.001s to 0.1s to 1s to 999.999s 9999.99s 99999.9s 99999s 99m59.99s 5 HoUr ñ 9999999 99959.9 0.1h to 0.1s to 99999.9h 999m59.9s \$ 5 Н ñ ñ! n ñ! n 999959 995959 999999 999999 999959 Timer range 1m to 0.1mto 1sto 1m to 1s to (HoUr/āl n/SEC) 99999.9m 9999h59m 99h59m59s 999999m 9999m59s ●4Digit type SEC 5*E* C SEC SEC 9.999 9999 99.99 999.9 9959 0.001s to 0.01s to 0.1s to 1s to 1s to 99.99s 999.9s 99m59s 9.999s 9999s \$ HoUr ΗĀ ñ! n ما ام 9999 9959 9999 999.9 1h to 1m to 1m to 0.1 m to 9999h 99h59m 9999m 999.9m UP/DOWN mode ※UP: Time proceeds from 0 to the setting value. UP ←→ dn (U-d) dn: Time proceeds from the setting value to 0. *Used for the indicator only. Indication mode *It is added that the feature which set the setting time when selecting totAL ↔ Hold ↔ ont.d Hold Or ont.d (d5P.ā) (Refer to J-26page '■Timer operation for the indicator'). Memory ***Used** for the indicator only. protection **ELr: Initializes time value when power is off.
rEL: Memorizes time value at the moment of power off. [Lr ←→ rE[(dAEA)ond ↔ ond.1 ↔ ond.2 ↔ FLY ↔ FLY.1 ↔ FLY.2 ↔ Int Output mode (oUE.ā) >Int[←→ nFd.l ←→ nFd ←→ oFd ←→ Int.2 ←→ Int. I OUT2 key: To shift flashing digit position of OUT2 output time output time value. *Setting range: 0.01 to 99.99sec. ★ key: To change OUT2 output time value. (oUE2) Set OUT1 one-shot output time. OUT1 key: To shift flashing digit position of OUT1 ★ Setting range: 0.01 to 99.99sec., Hold output time output time value. ★ key: To change OUT1 output time value. (oUt 1) Input logic ¬P¬: No-Voltage input *Check input logic value(PNP, NPN). (515)PnP: Voltage input Input *CTS/CTY: Set min. external INA, INH, RESET signal width. signal time → 20 ***CTM:** Set min. external INA, RESET, INHIBIT, [Unit: ms] (1 n.E)BATCH RESET signal width. * LoFF: Cancellation of the lock mode ► Lo[.1 Lo[. I: Locks ™ key. Lock key (Lo[Y])

Lo[.3: Locks , Ø, Ø, ⊗ keys.



Autonics J-22

(A) Photo electric sensor

(B)

Door/Area

Proximity sensor

Pressure

encode

Connector/ Socket

Temp.

(I) SSR/ Power controlle

(J) Counter

(K)

(L) Panel meter

Tacho/ Speed/ Pulse meter

(N) Display unit

Sensor controlle

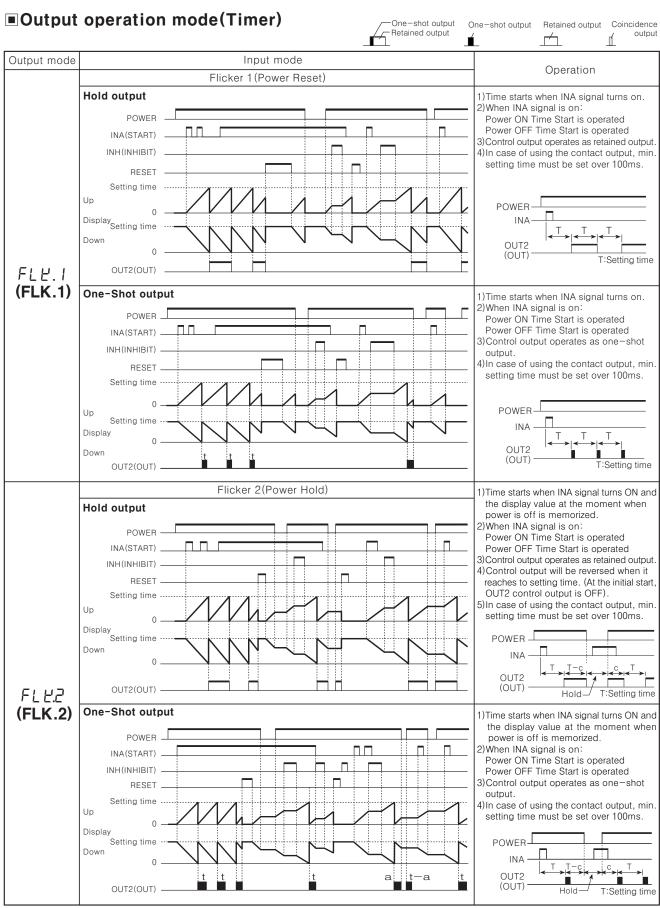
Switching power supply

(Q) Stepping motor & Driver & Controlle

(R) Graphic/ Logic panel

(S) Field network device

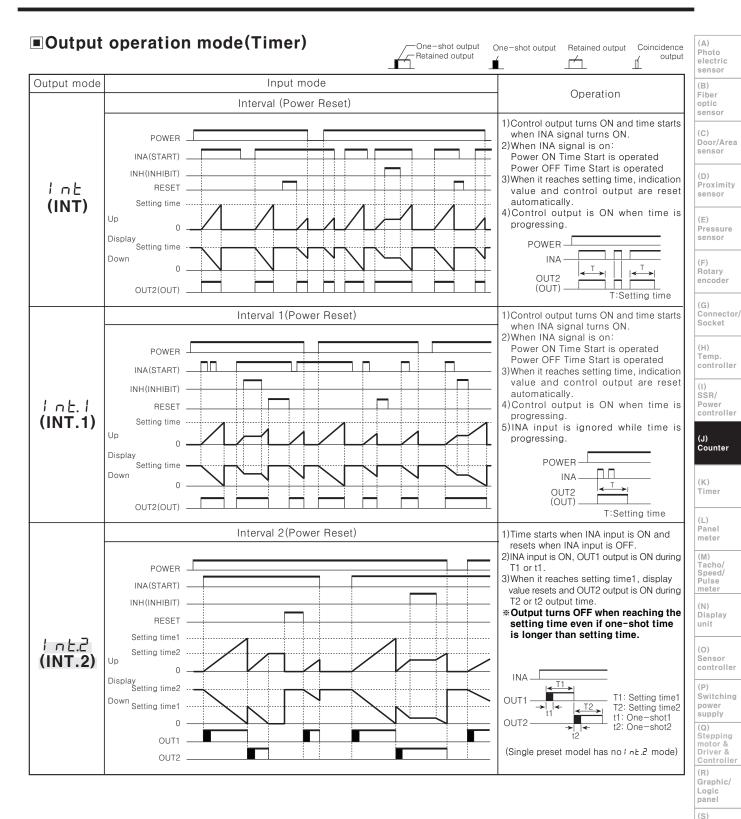
Production stoppage models & replacement



^{*}Power Reset: There is no memory protection. (Initializes the display value when power is off)

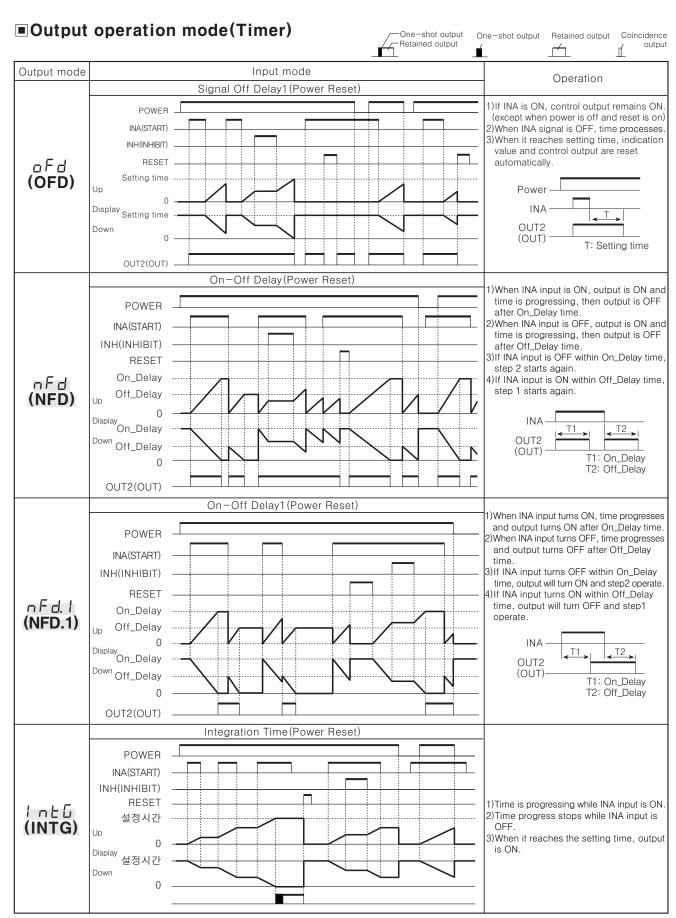
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

J-23 Autonics



Autonics J-24

Field network device (T) Production stoppage models & replacement



^{**}Power Reset: There is no memory protection. (Initializes the display value when power is off)

Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

J-25 Autonics

Photo electric sensor

(B)

(D)

Fiber

sensor

Door/Area

Proximity sensor

Pressure

Rotary

(G)

encoder

Connector/

Socket

Temp.

SSR/

Power

controlle

(J) Counter

(K)

(L)

(M)

Panel meter

Tacho/ Speed/

Pulse meter

Display

Sensor controller

Switching

(Q) Stepping motor & Driver & Controller

Graphic/

(R)

Logic

panel

device

Production

stoppage models & replacement

(S) Field network

power

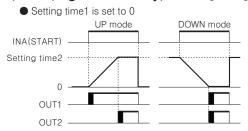
(N)

Timer

■Timer operation of the indicator(CT6S-I, CT6Y-I, CT6M-I) When memory protection setting is OFF POWER ___ ПП INA(START) -INH(INHIBIT) 1)Time starts when INA input is ON. 2) Setting value is initialized when Reset input П RESET Мах 3) Time progress stops when INHIBIT input is time range ON. Uр Λ 4) Resets when power is OFF. Display Мах time range Down LOLAL (TOTAL) When memory protection setting is ON POWER -INA(START) -1) Time starts when INA input is ON. INH(INHIBIT) 2) Setting value is initialized when Reset input RESET 3) Time progress stops while INHIBIT input time range is ON Uр 0 4) Display value at the moment of power OFF is memorized. Display Мах time range When memory protection setting is OFF POWER INA(START) 1)Time progresses when INA input is ON. INH(INHIBIT) 2) Time progress stops while INA input is OFF 3) When time reaches setting time, display RESET value will stop and flash. Setting time 4) When reset input is applied, display value Up is initialized. 5) Resets when power is OFF. Display Setting time Hold 0 When memory protection setting is ON (HOLD) POWER _ INA(START) 1) Time progresses when INA input is ON. 2)Time progress stops while INA input is OFF INH(INHIBIT) 3) When time reaches setting time, display RESET value will stop and flash 4) When reset input is applied, display value Setting time is initialized. Un 5) Display value the moment when power is 0 Display OFF is memorized. Setting time Down 0 When memory protection setting is OFF POWER -※ON time indicate mode of INA input ППП 1)Time reset start operates when INA input INA(START) turns ON. INH(INHIBIT) 2) Time progress stops while INA input is OFF RESET 3) When time progress stops and power is off, the display value is initialized. Setting time 4) If progress time is greater than setting Up time when INA input turns off, display 0 value flashes and operation stops until Display Setting time reset signal is applied. ont.d Down 0 (On Time When memory protection setting is ON Display) POWER _ ***ON** time indicate mode of INA input INA(START) 1)Time reset start operates when INA input INH(INHIBIT) turns ON. П 2) Time progress stops while INA input is OFF RESET 3) When time progress stops and power Setting time is off, the display value is memorized. 4)If progress time is greater than setting Uρ time when INA input turns off, display 0 value flashes and operation stops until Display Settina time reset signal is applied. Down

■Timer '0' time setting

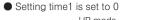
- OAvailable output operation mode to set '0' time setting ond, ond.I, ond2, nFd, nFd.I
- Operation according to output mode(at 0 time setting)
 - 1) OND(Signal ON Delay) mode [ond]

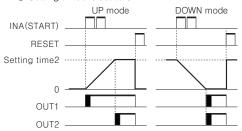


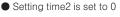
INA(START) -Setting time1 ----0 -OUT1

Setting time2 is set to 0

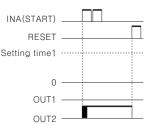
2) OND.1(Signal ON Delay 1) mode [ond. |]





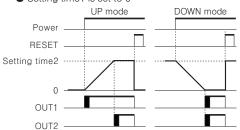


OUT2 -

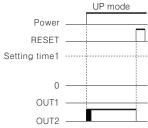


3) OND.2(Power ON Delay2) mode [ond.2]



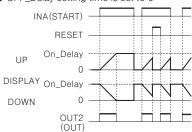




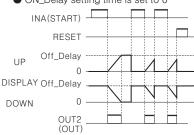


4) NFD(ON-OFF Delay) mode [nFd]



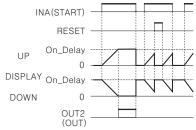


ON_Delay setting time is set to 0

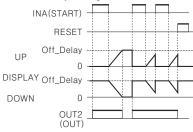


5) NFD.1(ON-OFF Delay1) mode [nFd.1]





ON_Delay setting time is set to 0



Setting value1(PS1) is higher than Setting value2(PS2)

In OND(and), OND.1(and.1) or OND.2(and.2) output mode

- •UP mode: If setting value of timer is higher than setting value 2, OUT1 will not turn ON.
- •DOWN mode: If setting value 1 of timer is higher than setting value2, OUT1 will turn ON immediately when start signal is applied.

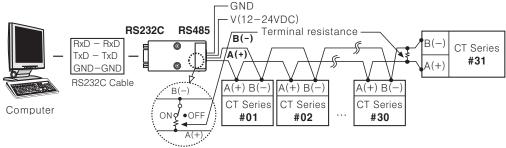
■ Communication mode

OParameter setting

(wo key: To select setting mode, ♥ or ♠ key: To change setting value)

Setting mode	Setting mode How to set	
Com. address (Addr)	C: To shift flashing digits of Com. address.☑ A: To change the flashing digits.	Setting range of com. address: 1 to 127If the same address is applied during multicom., it will not work correctly.
Com. speed (bP5)	24 ++ 48 ++ 96 ++ 192 ++ 384 t	*2400/4800/9600/19200/38400bps
Com. parity (アィヒリ)	nonE ←→ EuEn ←→ odd t	፠nanE: None EuEn: Even number add: Odd number
Com. stop bit (5 L P)	1 ← → 2	
Response waiting time (r 5 4.6)	 C: To shift flashing digits position of com. response waiting time. E ≥ C: To change the flashing digits position value. 	*Setting range according to com. speed. 2400bps 16ms to 99ms 4800bps 8ms to 99ms 9600bps 5ms to 99ms 19200bps 5ms to 99ms 38400bps 5msto 99ms
Com. write (にゅふご)	EnA ← → di SA	<pre>*EnA : Permits com. write(Enable) d! 5A : Prohibits com. write(Disable)</pre>

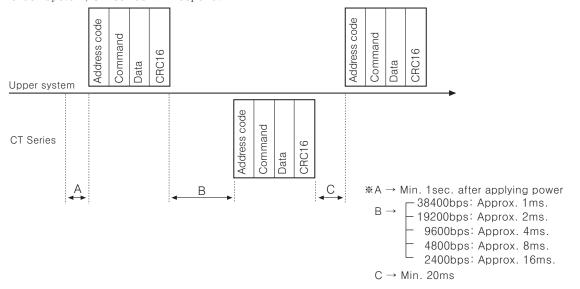
Application of system organization



*It is recommended to use communication converter, RS485 to Serial converter (SCM-38I, sold separately), USB to RS485 converter (SCM-US48I, sold separately). Please use a proper twist pair for RS485 communication.

Communication control ordering

- 1. The communication method is Modbus RTU(PI-MBUS-300-REV.J).
- 2. After 1sec. of power supply into the high order system, it starts to communicate.
- 3. Initial communication will be started by the high order system. When a command comes out from the high order system, CT series will respond.



(A) Photo electric sensor

(B) Fiber optic sensor

> (C) Door/Area

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

OCommunication command and block

The format of query and response

1) Read Coil Status(Func 01 H), Read Input Status(Func 02 H)

Query (Master)

Slave Address	Function	Starting Address		No. of	Points	Error (
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
			1				
-			1				

Response (Slave)

Slave Address	Function	n Byte Count Data Data		Data	Data Data		Check (16)		
Address		,				Low	High		
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		
CRC16									

2) Read Holding Registers(Func 03 H), Read Input Registers(Func 04 H)

CRC16

Query(Master)

Slave	Function	Starting Address		No. of	Points	_	ror Check CRC 16)		
Address		High	Low	High	Low	Low	High		
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		

•Response(Slave)

Slave	Function	Byte	Data			ata	Da	ita	(CRC 16)	
Address	I dilonon	Count	High	Low	High	Low	High	Low	Low	High
1Byte		1Byte								
-	CPC16									

3) Force Single Coil(Func 05 H)

Query(Master)

Slave Address	Function	Coil Address		Force	Data		Check C 16)		
Address		High	Low	High	Low	Low	High		
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		
▼									

●Response(Slave)

Slave Address	Function	Coil Address		Force	Data		r Check RC 16)	
Address		High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	
≺ CRC16								

4) Preset Single Register(Func 06 H)

●Query(Master)

		•								
	Slave	Function	Register Address		Prese	t Data		Error Check (CRC 16)		
	Address	T dilotion	High	Low	High	Low	Low	High		
	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		
İ	CRC16									

Response (Slave)

Slave Address	Function	Register Address		Prese	t Data	Error ((CRC			
Address	T dilotion	High	Low	High	Low	Low	High		
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		
▼ CRC16									

5) Preset Multiple Registers(Func 10 H)

Query (Master)

Slave Address	Function	Add	rting Iress	No. Reg		Byte Count		ata	Data		Error Check (CRC 16)	
		High	Low	High	Low		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
CRC16 CRC16												

•Response(Slave)

Slave	Function	Starting Address		No. of	Register	Error (
Address		High	Low	High	Low	Low	High		
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte		
CRC16									

6) Application

Read Coil Status (Func 01 H)

Master reads OUT2 00002(0001H) to 00003(0002H), OUT1 output status(ON: 1, OFF: 0) from the Slave (Address 01).

Query (Master)

	Slave Address	Function	Starting Address		No. of	Points	s Error Checl (CRC 16)	
			High	Low	High	Low	Low	High
	01 H	01 H	00 H	01 H	00 H	02 H	EC H	0B H

On slave side OUT2 00003(0002H): OFF, OUT1 00002(0001H): ON

•Response(Slave)

Slave Address	ss Function	Byte Count	Data (00003 to	Error (
		,	00001)	Low	High
01 H	01 H	01 H	02 H	D0 H	49 H

Read Input Register (Func 04 H)

Master reads preset value 21004(03EBH) to 21005 (03ECH) of counter/timer, Slave (Address 15).

Query (Master)

Slave Address	Function	Starting	Address	No. of	Points	Error (CR	
Address	Address		Low	High	Low	Low	High
0F H	04 H	03 H	EB H	00 H	02 H	00 H	95 H

In case that the present value is 123456(0001 E240 H) in slave side, 31004(03EBH): E240 H, 31005(03ECH): 0001H

•Response(Slave)

Slave Address	Function	Byte Count	Da	ata	Da	ata	Error (CR	
	_,	High	Low	High	Low	Low	High	
0F H	04 H	04 H	E2 H	40 H	00 H	01 H	E2 H	28 H

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Modbus Mapping Table

1) Reset/Output

	No.(Address)	Func	Explanation	Setting range	Notice
	00001 (0000)	01/05	Reset	0:OFF 1:ON	
	00002(0001)	01	OUT2 output	0:OFF 1:ON	
	00003(0002)	01	OUT1 output	0:OFF 1:ON	
	00004(0003)	01	BATCH output	0:OFF 1:ON	For BATCH
ļ	00005(0004)	01/05	BATCH resets	0:OFF 1:ON	output model

2) Terminal input status

No.(Address)	Func	Explanation	Setting range	Notice
10001 (0000)	02	INA input status	0:OFF 1:ON	
10002(0001)	02	INB input status	0:OFF 1:ON	
10003(0002)	02	INHIBIT input status	0:OFF 1:ON	Terminal input
10004(0003)	02	RESET input status	0:OFF 1:ON	
10005(0004)	02	BATCH RESET input status	0:OFF 1:ON	

3) Product Information

Producti	11101	mation		
No.(Address)	Func	Explanation	Factory default	Notice
30001~30100	04	Reserved	_	
30101(0064)	04	Product number H	-	Model ID
30102(0065)	04	Product number L	-	Modelid
30103(0066)	04	Hardware version	-	
30104(0067)	04	Software version	Í	
30105(0068)	04	Model no. 1	"CT"	
30106(0069)	04	Model no. 2	"6M"	
30107(006A)	04	Model no. 3	"-2"	
30108(006B)	04	Model no. 4	"PT"	
30109(006C)	04	Reserved	-	
30110(006D)	04	Reserved	-	
30111(006E)	04	Reserved	-	
30112(006F)	04	Reserved	-	
30113(0070)	04	Reserved	-	
30114(0071)	04	Reserved	-	
30115(0072)	04	Reserved	-	
30116(0073)	04	Reserved	-	
30117(0074)	04	Reserved	-	
30118(0075)	04	Coil Status Start Address	0000	
30119(0076)	04	Coil Status Quantity	_	
30120(0077)	04	Input Status Start Address	0000	
30121 (0078)	04	Input Status Quanity	-	
30122(0079)	04	Holding Register Start Address	0000	
30123(007A)	04	Holding Register Quantity	-	
30124(007B)	04	Input Register Star Address	0064	
30125(007C)	04	Input Register Quantity	_	

4) Monitoring data

No.(Address)	Func	1	Setting range	Notice	
		BA.O LED display status	0:OFF 1:ON	Bit 5	
		OUT2 LED display status	0:OFF 1:ON	Bit 6	
		OUT1 LED display status	0:OFF 1:ON	Bit 7	
		BA.S LED display status	0:OFF 1:ON	Bit 10	
31001 (03E8)	04	LOCK LED display status	0:OFF 1:ON	Bit 11	
		PS2 LED display status	0:OFF 1:ON	Bit 12	
		PS1 LED display status	0:OFF 1:ON	Bit 13	
		TMR LED display status	0:OFF 1:ON	Bit 14	
		CNT LED display status	0:OFF 1:ON	Bit 15	
31002(03E9)	0.4	Present value		For BATCH	
31003(03EA)	04	of BATCH counter	0 to 999999	output model	
31004(03EB)	04	Present value	Counter 6Digit type: -99999 to 999999	Use counter and timer	
31005(03EC)		counter/timer	4Digit type:-999 to 9999 Timer: Within time setting range	in common	
31006(03ED)	04	Display unit	Counter:decimal point of display value Timer:Time range	Counter: 40058 Data Timer: 40102 Data	
31007(03EE)	04	PS(2)	Counter 6Digit type: -99999 to 999999	Use counter	
31008(03EF)	04	setting value	4Digit type: -999 to9999 Timer: Within time setting range	and timer in common	
31009(03F0)		PS1	Counter 6Digit type: -99999 to 999999	Use counter	
31010(03F1) 04		setting value		and timer in common	
31011(03F2)	0.4	Setting value of BATCH	0.1000000	Use counter	
31012(03F3)	04	counter	0 to 999999	and timer in common	
31013(03F4)	04	Checking the input logic	0: NPN, 1:PNP		

●Date format of 31001(03E8) address bit

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CNT	TMR	PS1	PS2	Lock	BA.S	-	-	OUT1	OUT2	BA.O	-	-	-	-	-
0 or 1	0 or 1	0 or 1	0 or 1	0 or 1	0 or 1	0	0	0 or 1	0 or 1	0 or 1	0	0	0	0	0

**2Words data format: Upper data has high number address.
Ex)31004: Present Value(Low Word),
31005: Present Value(High Word)

5) Preset value setting group

No.(Address)	Func	Explanation	Setting range	Notice
40001 (0000)	03 06	PS2 setting value	Counter	Use counter and timer
40002(0001)	16	PS setting value	6Digit type:0 to 999999	in common
40003(0002)	03 06	DS1 sotting value	4Digit type:0 to 9999 Timer: Within time	Use counter and timer
40004(0003)	16	1 31 setting value	setting range	in common
40005(0004)	03 06	BATCH counter	0.40.00000	Use counter
40006(0005)	16	setting value	0 to 999999	and timer in common

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

Proximity sensor

Pressure sensor

(F)
Rotary
encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L)
Panel
meter

(M)
Tacho/
Speed/
Pulse
meter

Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

Graphic/ Logic panel

Field network device

(T) Production stoppage models & replacement

6) Function setting mode (Counter group)

No.(Address)	Func	Explanation	Setting range	Notice
40051 (0032)	03/06/16	Counter/Timer(E-E)	0: EoUn 1: E! ñE	Use counter and timer in common
40052(0033)	03/06/16	Input mode(i n)	0: UP 5: dn-2 1: UP- 1 6: Ud-R 2: UP-2 7: Ud-b 3: dn 8: Ud-C 4: dn- 1	
40053(0034)	03/06/16	Indication mode(d: 5n)	O: EoEAL 1: HoLd	For the indicator
40054(0035)	03/06/16	Output mode(alltā)	0: F 3: r 6: 9 9: Ł 1: n 4: Ł 7: R 10: d 2: C 5: P 8: 5	
40055(0036)	03/06/16	Maximum counting speed (EPS)	0: 1 2: 15 4: 105 1: 30 3: 55	
40056(0037)	03/06/16	OUT2(OUT) Output time	000 I to 9999	Unit: ×10ms
40057(0038)	03/06/16	OUT1 Output time	000 I to 9999	Unit: ×10ms
40058(0039)	03/06/16	Decimal point(dP)	0: 2: 4: 1: 3: 5:	4Digit type 0: 1:2:3:
40059(003A)	03/06/16	Min. reset time(-5£)	0: 1 1: 20	Unit: ms
40060(003B)	03/06/16	Prescale decimal point position(5[L.d)	1: 3: 5: 2: 4:	4Digit type 1: 2: 3:
40061 (003C)	03/06/16	Prescale value(5£L)	6Digit type: 0.0000 I to 999999	Connected with prescale
40062(003D)	03/00/10	riescale value(3LL)	4Digit type: 0.00 / to 9999	decimal point position
40063(003E)	03/06/16	Start value(5£ r £)	6Digit type: 000000 to 999999	Connected with decimal
40064(003F)			4Digit type: 0000 to 9999	point position of display value
40065(0040)	03/06/16	Memory protection(dRLR)	0: ELr 1: rEE	Use counter and timer
40066(0041)	03/06/16	Lock key(LoEt)	0: L.oFF 1: LoC. 1 2: LoC.2 3: LoC.3	in common

7) Function setting mode (Timer group)

No.(Address)	Func	Explanation	Setting range	Notice
40101(0064)	03/06/16	Counter/Timer(E-E)	0: EoUn 1: E! ñE	Use counter and timer in common
40102(0065)	03/06/16	Time range (Hollr /ก็! ก/SEC)	4Digit type 0: 0.001s to 9.999s 5: 0.1m to 999.9m 1: 0.01s to 99.99s 6: 1m to 9999m 2: 0.1s to 999.9s 7: 1m to 99959m 3: 1s to 9999s 8: 1h to 9999h 4: 1s to 99m59s 6Digit type 0: 0.001s to 999.999s 6: 1s to 9999m59s 1: 0.01s to 9999.99s 7: 0.1m to 99999.9m 2: 0.1s to 99999.9s 8: 1m to 999999m 3: 1s to 999999 9: 1s to 99h59m59s 4: 0.01s to 99m59.99s 10: 1m to 99999.9h 5: 0.1s to 999m59.9s 11: 0.1h to 99999.9h	
40103(0066)	03/06/16	Up/Down mode (U-d)	0: UP 1: dn	
40104(0067)	03/06/16	Output mode (aUEñ)	0: ond 3: FLE 7: I nE.I 10: nFd 1: ondI 4: FLE.I 8: I nE.Z 11: nFd.I 2: ondZ 5: FLE.Z 9: oFd 12: I nE.G	
40105(0068)	03/06/16	OUT2(OUT) Output time (๑๕৮२)	0000 to 9999 (0 : Hold)	Unit: ×10ms
40106(0069)	03/06/16	OUT1 Output time (oUt I)	0000 to 9999 (0 : Hold)	Unit: ×10ms
40107(006A)	03/06/16	Input signal time(I nt)	0: 1 1: 20	Unit: ms
40108(006B)	03/06/16	Memory protection(dRLR)	0: ELr 1: rEE	Use counter and timer
40109(006C)	03/06/16	Lock key(Lo[t]	0: L.oFF 1: LoE. 1 2: LoE.2 3: LoE.3	in common
40110(006D)	03/06/16	Indication mode(d5P.ā)	O: totAL 1: Hold 2: ont.d	For the indicator

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8) Function setting mode (Communication group)

No.(Address)	Func	Explanation	Setting range	Notice
40151 (0096)	03/06/16	Com. address(Addr)	1 to 127	
40152(0097)	03/06/16	Com. speed(bP5)	0:24 1:48 2:96 3:192 4:384	Unit: ×100bps
40153(0098)	03/06/16	Com. parity(Pィヒリ)	O:nonE 1:EuEn 2:odd	
40154(0099)	03/06/16	Stop bit(5£P)	0: / 1: 2	
40155(009A)	03/06/16	Response waiting time (rら止り)	05 to 99	Unit : ms
40156(009B)	03/06/16	Com. writing([añ.4)	0: EnA 1: dl 5A	

©Exception processing

When communication error occurs, the highest bit of received function is set to 1, then sends response command and transmits exception code.

Slave Address	Function L 90H	Exception Code	Error Check(CRC16)		
Slave Address	re Address Function+80H	Exception code	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	

- •Illegal Function (Exception Code: 01H): Not supporting command
- •Illegal Data Address (Exception Code: 02H): Mismatch between the number of asked data and the number of transmittable data.
- •Illegal Data Value (Exception Code: 03H): Mismatch between asked the number of data and transmittable the number of data in device
- •Slave Device Failure (Exception Code: 04H): Command is processed incorrectly.

Example)

Master reads output status (ON:1, OFF:0) of non existing coil 01001 (03E8 H) from Slave (Address17).

Query (Master)

Slave Address	Function	Starting Address		No. of Points		Error Check(CRC16)	
		High	Low	High	Low	Low	High
11 H	01 H	03 H	E8 H	00 H	01 H	## H	## H

Response (Slave)

Clave Address	Function 0011	Evention Code	Error Check(CRC16)	
Slave Address	Function + 80H	Exception Code	Low	High
11H	81H	02H	## H	## H

■ Read and write of parameter value using communication

ORead of the parameter area

00002(OUT2), 00003(OUT1), 00004(BA, 0), 10001 to 10005(Terminal input), 30101 to 30125(Product information), 31001 to 31013(Monitoring data)

Read and write of the parameter area

00001 (Reset starts), 00005 (BATCH Reset starts), 40001 to 40006 (Setting value saving group), 40051 to 40066 (Counter setting group), 40101 to 40110 (Timer setting group), 40151 to 40156 (Communication setting group)

Read of communication

Read parameter value using communication. (Function: 01H, 02H, 03H, 04H) It is able to read communication regardless of permitting/prohibiting communication writing.

○Communication write

Change parameter value using communication. (Function: 05H, 06H, 10H)

- •When change the parameter setting value of 'IFunction setting mode Counter group' or 'IFunction setting mode Timer group' using communication, reset indication will flash in 3 sec. and display value will be reset. (Counting display value and progress time before changing parameter setting value are not saved.)
- ●When change the parameter setting value of '■Preset value setting group' or '■Function setting mode Communication group' using communication, counting display value or progress time will not be reset.
- •In prohibit writing communication setting ([a, 2] = 1:d| 5A), a write command does not process.
- •If set value beyond the setting range, this setting value is substituted for the value within the setting range and then memorized.

(A) Photo electric sensor

(B) Fiber optic

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

Panel meter (M) Tacho/

(L)

Pulse meter

unit

(0)

(P) Switching

(Q) Stepping motor & Driver & Controlle

power

(R) Graphic/ Logic panel

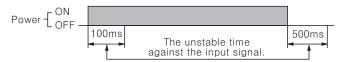
(S) Field network device

(T) Production stoppage models & replacement

CT Series

■ Proper usage

OThe power ON/OFF



•The power ON/OFF

Power voltage rises for 100ms after power on and falls for 500ms after power off. Therefore be sure to apply input signal after 100ms and power turns on again after 500ms when power turns off.

•Be sure to use insulated and resistive voltage /current or Class2 supply power device to input 24VAC/24-48VDC power supply model.

OInput signal line

- Use as short a cable from the sensor to this unit as possible.
- •Use shielded cable for long input line.
- •Wire as seaparating input line from the power line.

When selecting input logic

Be sure that supply power is off when selecting input logic, then select logic input according to input logic changing method.

Contact count input(When it is used as Counter)

If apply contact input at high speed mode(1k, 5k, 10k), it may cause miscount by chattering.

Therefore set low speed mode(1cps or 30cps) at contact input.

- When test dielectric voltage and insulation resistance of the control panel with this unit installed.
 - •Please isolate this unit from the circuit of control panel.
 - •Please make all terminals of this unit short-circuited.

ODo not use below places.

- •Place where there are severe vibration or impact.
- •Place where strong alkalis or acids are used.
- •Place where there are direct ray of the sun.
- •Place where strong magnetic field or electric noise are generated.

OInstallation environment

- •It shall be used indoor.
- •Altitude Max. 2000m
- ●Pollution Degree 2
- •Installation Category II

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